

March 23rd

#0

→ Extensions

2.10: Note that ^{the} book calls it more general "for the Agent", but in 2.10.1 it is more general for P.

2.11: Contracting before type revealed to A

2.12: next time...

not
on
reading
list

2.13: A few words regarding concavity or not ↔ averaging or not cf 2.11

2.14: A few words on # states of the world

2.15: You might want me to elaborate on seminar problem #2 ?

2.10

2.10.1 Covered last time

2.10.2 Extension: type-dependent utility S_i ($i=0,1$) for P.

→ problem as before, but with S_0, S_1 distinguished.

→ new feature: $S_0 \neq S_1$ may lead to $q_0 \geq q_1$ (under S-M) being binding.

→ this may happen if $S_1^1 > S_0^1$ in optimum

→ interpretation: type 0 is more quantity-efficient, but you prefer type 1's goods for quality.

(→ good explanation why both types exist)

Recall when $S_0 = S_1 = S$:

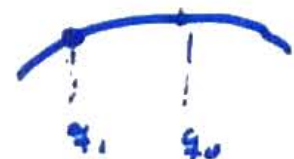
→ S-M: $C_1' \geq C_0'$, which
will imply $q_0 \geq q_1$.

→ If $S_0' > S_1'$, this effect
is enhanced. Ex: put $C_1 = C_0 = C$

$$\text{At } q_0: S_0' = C_0'$$

$$\text{At } q_1: S_1' = C_1' + 0$$

At q_1 , $S_0' > C_1'$ and by

concavity: $S_0' - C_1' > 0 \Rightarrow$ 

→ But if $S_1' > S_0'$, it will
have the opposite effect:
lowering $q_0 - q_1$.

→ If this effect is strong enough,
we must pool $q_0 = q_1 = q$,
because under S-M, $q_0 < q_1$
is not incentive feasible.

(Note: If $C_1' \leq C_0'$ -
with opposite constant sign
- then the effects are reversed.)

The maths: Assume S-M applies.

Form the Lagrangian

$$v(S_0(q_0) - C_0(q_0)) + (1-v)(S_1(q_1) - C_1(q_1)) - v\Delta C$$

$$+ \underbrace{\lambda(q_0 - q_1)}_{\text{Constr. } q_0 - q_1 \geq 0} + \mu q_1$$

$q_1 \geq 0.$

(Recall Compl. Slackness)

1st o.c.'s:

$$\text{At } q_0: S_0' - C_0' = -\frac{\lambda}{v}$$

$$\text{At } q_1: S_1' - C_1' = \frac{v}{1-v} \Delta C' + (\lambda - \mu)$$

Cases: • $\lambda = \mu = 0$ will be chosen if incentive feasible

• $\mu > 0 \Rightarrow q_1 = 0$, just as before

• $\lambda > 0 = \mu$: $q_0 = q_1$. Insert:

$$v S_0 + (1-v) S_1 \leftarrow -C_1$$

$$=: \tilde{S}$$

Adapt when $\tilde{S}' = C_1'$

2.10.3 More goods.

#4

q_0 vector in \mathbb{R}^n | Differs
 q_1 — " — | from
book

Write D_k for partial derivative wrt ~~S~~
the k^{th} component $q^{(k)}$.

Turns out, by inspecting calculations:
need to consider the " $q_0 \succeq q_1$ " which
in the single-good case was implied
by $S = M$ (which now is a comp.-wise property)

Compatibility leads to $\Delta C(q_0) \succeq \Delta C(q_1)$.

Denote ΔC by $\underline{\Phi}$. Need $\underline{\Phi}(q_0) \succeq \underline{\Phi}(q_1)$

Both q_i and $\nabla \underline{\Phi}$ vectors. No " \succeq ".

But previous solutions suggest:

$$\nabla(S_0 - C_0) = 0 \text{ at } q_0$$

$$\nabla(S_1 - C_1) = \frac{v}{1-v} \nabla \underline{\Phi} \text{ at } q_1.$$

This solves if inc. feas.

$$\text{Suff. cond: } \left\{ \begin{array}{l} D_k \underline{\Phi} \geq 0, \text{ all } k \\ S_0 = S_1 = S \end{array} \right.$$

2.11 Contracting before type known to A (and P).

Book: increasing level of generality.

Here: general case (others below)

Setup: vNM utility functions

u for A, v for P. (as book).

- Notation: In order not to confuse u vs U , v vs v , write
 - p for v
 - $y_i = t_i - C_i(q_i)$
to be inserted for t_i
 - $x_i = S_i(q_i) - C_i(q_i) - y_i$
not to be inserted until after differentiating.
- Ex ante participation constraint

$$0 \leq E[u(\cdot)] = p u(y_0) + (1-p) u(y_1),$$
 multiplier = ~~μ~~ μ
- Ex post compatibility:

$$y_0 \geq y_1 + \Phi, \quad \text{multiplier} = \lambda$$

Lagrangian for the non-pooling case (if e.g. S-M, and this approach yields $q_0 < q_1$, then solve separately the case $q_0 = q_1 = q$):

$$\begin{aligned}
 & p v(S_0(q_0) - C_0(q_0) - y_0) \\
 & + (1-p) v(S_1(q_1) - C_1(q_1) - y_1) \\
 & + \mu \cdot (p u(y_0) + (1-p) u(y_1)) \\
 & + \lambda \cdot (y_0 - y_1 - \Phi(q_1))
 \end{aligned}$$

1st o.c.

$$y_0: p v'(x_0) = \mu p u'(y_0) + \lambda$$

$$y_1: (1-p) v'(x_1) = \mu (1-p) u'(y_1) - \lambda$$

add to get $\mu = E v' / E u'$

Cramér's rule:
$$\lambda = \frac{p(1-p)}{E u'} \begin{vmatrix} v'(x_0) & u'(y_0) \\ v'(x_1) & u'(y_1) \end{vmatrix}$$

1st o.c.:

$$\text{at } q_0: p v'(x_0) \cdot (S_0' - C_0') = 0$$

$$\text{at } q_1: \underbrace{(1-p) v'(x_1) \cdot (S_1' - C_1')}_{> 0} = \lambda \Phi'$$

$\lambda \geq 0$, so downward shift in q_1 (except case $\lambda=0$ which implements full information q_1)

At q_1 :

"usual"
expr.

#8 corrected

$$S_1' - C_1' = \frac{p}{1-p} \Phi' \cdot \frac{1-p}{v'(x_1) E u'} \begin{vmatrix} v'(x_0) & u'(y_0) \\ v'(x_1) & u'(y_1) \end{vmatrix}$$

Cases - with none of the players risk-seeking ?

* Case P risk neutral.

$$\text{Determinant} = (u(y_1) - u(y_0)) v'$$

and at q_1 :

$$S_1' - C_1' = \frac{p}{1-p} \Phi' \cdot (1-p) \frac{u'(y_1) - u'(y_0)}{E u'}$$

turns out: < 1

* Case P risk averse, A risk neutral

$$\text{Determinant} = (v'(x_0) - v'(x_1)) u'$$

$$\lambda \geq 0 \Rightarrow \text{det.} \geq 0 \Rightarrow x_0 \leq x_1$$

If $S_1 = S_0$ this turns out \Leftrightarrow to

~~$$S(q_0) - C_0(q_0) \leq S(q_1) - C_0(q_1)$$~~

$$S(q_0) - C_0(q_0) \leq S(q_1) - C_0(q_1)$$

but q_0 maximizes $S - C_0$. So $x_0 = x_1$,

and $\lambda = 0$. We get $S_1' - C_1' = 0$ at q_1 .

* Other cases do not simplify

Brief on signals. By example.

P says: "I want to check your financial statement".

(- assumed verifiable
(can be weakened!))

Why would P want this information?

Because it (possibly) correlates with type.

E.g.: assume each agent has either surplus K or 0 (break even)

and that the efficient agent is more likely to have K than the inefficient.

→ 4 states of the world:

Type Signal	eff.	ineff.
0	.	.
K	.	.

→ 2 compatibility constraints & 2 participation constraints — enough for 4 contracts (with =).

→ ~~to~~ precisely unless signal is uninformative.