Lecture 19. 19. mars 2018

4.7 Connection coefficients $\Gamma^{\alpha}_{\mu\nu}$ and structure coefficients $c^{\alpha}_{\mu\nu}$ in a Riemannian (torsion free) space

The commutator of two vectors, \vec{u} and \vec{v} , expressed by covariant directional derivatives is given by:

$$[\vec{u}, \vec{v}] = \nabla_{\vec{u}}\vec{v} - \nabla_{\vec{v}}\vec{u} \tag{4.91}$$

Let $\vec{u} = \vec{e_{\mu}}$ and $\vec{v} = \vec{e_{\nu}}$. We then have:

$$[\vec{e_{\mu}}, \vec{e_{\nu}}] = \nabla_{\mu} \vec{e_{\nu}} - \nabla_{\nu} \vec{e_{\mu}}. \tag{4.92}$$

Using the definitions of the connection and structure coefficients we get:

$$c^{\alpha}_{\mu\nu}\vec{e_{\alpha}} = (\Gamma^{\alpha}_{\nu\mu} - \Gamma^{\alpha}_{\mu\nu})\vec{e_{\alpha}} \tag{4.93}$$

Thus in a torsion free space

$$c^{\alpha}_{\ \mu\nu} = \Gamma^{\alpha}_{\ \nu\mu} - \Gamma^{\alpha}_{\ \mu\nu} \tag{4.94}$$

In coordinate basis we have

$$\vec{e_{\mu}} = \frac{\partial}{\partial x^{\mu}} \,, \quad \vec{e_{\nu}} = \frac{\partial}{\partial x^{\nu}}$$
 (4.95)

4.8.2 Covariant differentiation of forms

Definition 4.8.2 (Covariant directional derivative of a one-form field) Given a vector field \vec{A} and a one-form field $\underline{\alpha}$, the covariant directional derivative of $\underline{\alpha}$ in the direction of the vector \vec{u} is defined by:

$$(\nabla_{\vec{u}}\underline{\alpha})(\vec{A}) \equiv \nabla_{\vec{u}}[\underline{\alpha}(\vec{A})] - \underline{\alpha}(\nabla_{\vec{u}}\vec{A})$$
(4.103)

Let $\underline{\alpha} = \underline{\omega}^{\mu}$ (basis form), $\underline{\omega}^{\mu}(\vec{e_{\nu}}) \equiv \delta^{\mu}{}_{\nu}$ and let $\vec{A} = \vec{e_{\nu}}$ and $\vec{u} = \vec{e_{\lambda}}$. We then have:

$$(\nabla_{\lambda}\underline{\omega}^{\mu})(\vec{e_{\nu}}) = \nabla_{\lambda}[\underbrace{\underline{\omega}^{\mu}(\vec{e_{\nu}})}_{\delta^{\mu}{}_{\nu}}] - \underline{\omega}^{\mu}(\nabla_{\lambda}\vec{e_{\nu}})$$

$$(4.104)$$

The covariant directional derivative ∇_{λ} of a constant scalar field is zero, $\nabla_{\lambda}\delta^{\mu}{}_{\nu}=0$. We therefore get:

$$\begin{split} (\nabla_{\!\lambda}\underline{\omega}^{\mu})(\vec{e_{\nu}}) &= -\underline{\omega}^{\mu}(\nabla_{\!\lambda}\vec{e_{\nu}}) \\ &= -\underline{\omega}^{\mu}(\Gamma^{\alpha}_{\ \nu\lambda}\vec{e_{\alpha}}) \\ &= -\Gamma^{\alpha}_{\ \nu\lambda}\underline{\omega}^{\mu}(\vec{e_{\alpha}}) \\ &= -\Gamma^{\alpha}_{\ \nu\lambda}\delta^{\mu}_{\ \alpha} \\ &= -\Gamma^{\mu}_{\ \nu\lambda} \end{split} \tag{4.105}$$

The contraction between a one-form and a basis vector gives the components of the one-form, $\underline{\alpha}(\vec{e_{\nu}}) = \alpha_{\nu}$. Equation (4.105) tells us that the ν -component of $\nabla_{\!\lambda}\underline{\omega}^{\mu}$ is equal to $-\Gamma^{\mu}_{\nu\lambda}$, and that we therefore have

$$\nabla_{\!\lambda}\underline{\omega}^{\mu} = -\Gamma^{\mu}_{\nu\lambda}\underline{\omega}^{\nu} \tag{4.106}$$

Equation (4.106) gives the directional derivatives of the basis forms. Using the product of differentiation gives

$$\nabla_{\lambda}\underline{\alpha} = \nabla_{\lambda}(\alpha_{\mu}\underline{\omega}^{\mu})$$

$$= \nabla_{\lambda}(\alpha_{\mu})\underline{\omega}^{\mu} + \alpha_{\mu}\nabla_{\lambda}\underline{\omega}^{\mu}$$

$$= \vec{e}_{\lambda}(\alpha_{\mu})\underline{\omega}^{\mu} - \alpha_{\mu}\Gamma^{\mu}_{\nu\lambda}\underline{\omega}^{\nu}$$
(4.107)

Definition 4.8.3 (Covariant derivative of a one-form)

The covariant derivative of a one-form $\underline{\alpha} = \alpha_{\mu} \underline{\omega}^{\mu}$ is therefore given by Equation (4.108) below, when we let $\mu \to \nu$ in the first term on the right hand side in (4.107):

$$\nabla_{\lambda}\underline{\alpha} = \left[\vec{e_{\lambda}}(\alpha_{\nu}) - \alpha_{\mu}\Gamma^{\mu}_{\nu\lambda}\right]\underline{\omega}^{\nu} \tag{4.108}$$

The covariant derivative of the one-form components α_{μ} are denoted by $\alpha_{\nu;\lambda}$ and are defined by

$$\nabla_{\!\!\lambda}\underline{\alpha} \equiv \alpha_{\nu;\lambda}\underline{\omega}^{\nu} \tag{4.109}$$

It then follows that

$$\alpha_{\nu;\lambda} = \vec{e_{\lambda}}(\alpha_{\nu}) - \alpha_{\mu} \Gamma^{\mu}_{\nu\lambda} \tag{4.110}$$

It is worth to note that $\Gamma^{\mu}_{\nu\lambda}$ in Equation (4.110) are not Christoffel symbols. In coordinate basis we get:

$$\alpha_{\nu;\lambda} = \alpha_{\nu,\lambda} - \alpha_{\nu} \Gamma^{\mu}_{\lambda\nu} \tag{4.111}$$

where $\Gamma^{\mu}_{\lambda\nu} = \Gamma^{\mu}_{\nu\lambda}$ are Christoffel symbols.

4.8.3 Generalization for tensors of higher rank

Definition 4.8.4 (Covariant derivative of a tensor)

Let A and B be two tensors of arbitrary rank. The covariant directional derivative along a basis vector $\vec{e_{\alpha}}$ of a tensor $A \otimes B$ of arbitrary rank is defined by:

$$\nabla_{\lambda}(A \otimes B) \equiv (\nabla_{\lambda}A) \otimes B + A \otimes (\nabla_{\lambda}B) \tag{4.112}$$

We will use (4.112) to find the formula for the covariant derivative of the components of a tensor of rank 2:

$$\nabla_{\alpha} S = \nabla_{\alpha} (S_{\mu\nu} \underline{\omega}^{\mu} \otimes \underline{\omega}^{\nu})$$

$$= (\nabla_{\alpha} S_{\mu\nu}) \underline{\omega}^{\mu} \otimes \underline{\omega}^{\nu} + S_{\mu\nu} (\nabla_{\alpha} \underline{\omega}^{\mu}) \otimes \underline{\omega}^{\nu} + S_{\mu\nu} \underline{\omega}^{\mu} \otimes (\nabla_{\alpha} \underline{\omega}^{\nu})$$

$$= (S_{\mu\nu,\alpha} - S_{\beta\nu} \Gamma^{\beta}_{\mu\alpha} - S_{\mu\beta} \Gamma^{\beta}_{\nu\alpha}) \underline{\omega}^{\mu} \otimes \underline{\omega}^{\nu}$$

$$(4.113)$$

where $S_{\mu\nu,\alpha} = \vec{e}_{\alpha}(S_{\mu\nu})$. Defining the covariant derivative $S_{\mu\nu,\alpha}$ by

$$\nabla_{\alpha} S = S_{\mu\nu;\alpha} \underline{\omega}^{\mu} \otimes \underline{\omega}^{\nu} \tag{4.114}$$

we get

$$S_{\mu\nu;\alpha} = S_{\mu\nu,\alpha} - S_{\beta\nu} \Gamma^{\beta}_{\mu\alpha} - S_{\mu\beta} \Gamma^{\beta}_{\nu\alpha} \tag{4.115}$$

For the metric tensor we get

$$g_{\mu\nu;\alpha} = g_{\mu\nu,\alpha} - g_{\beta\nu} \Gamma^{\beta}_{\mu\alpha} - g_{\mu\beta} \Gamma^{\beta}_{\nu\alpha} \tag{4.116}$$

From

$$g_{\mu\nu} = \vec{e_{\mu}} \cdot \vec{e_{\nu}} \tag{4.117}$$

we get:

$$g_{\mu\nu,\alpha} = (\nabla_{\alpha}\vec{e_{\mu}}) \cdot \vec{e_{\nu}} + \vec{e_{\mu}}(\nabla_{\alpha}\vec{e_{\nu}})$$

$$= \Gamma^{\beta}_{\mu\alpha}\vec{e_{\beta}} \cdot \vec{e_{\nu}} + \vec{e_{\mu}} \cdot \Gamma^{\beta}_{\nu\alpha}\vec{e_{\beta}}$$

$$= g_{\beta\nu}\Gamma^{\beta}_{\mu\alpha} + g_{\mu\beta}\Gamma^{\beta}_{\nu\alpha}$$
(4.118)

This means that

$$g_{\mu\nu;\alpha} = 0 \tag{4.119}$$

So the metric tensor is a (covariant) constant tensor.

4.9 The Cartan connection

Definition 4.9.1 (Exterior derivative of a basis vector)

$$\underline{d}\vec{e}_{\mu} \equiv \Gamma^{\nu}_{\mu\alpha}\vec{e}_{\nu} \otimes \underline{\omega}^{\alpha} \tag{4.120}$$

Exterior derivative of a vector field:

$$\underline{d}\vec{A} = \underline{d}(\vec{e}_{\mu}A^{\mu}) = \vec{e}_{\nu} \otimes \underline{d}A^{\nu} + A^{\mu}\underline{d}\vec{e}_{\mu}$$
(4.121)

In arbitrary basis:

$$\underline{d}A^{\nu} = \vec{e}_{\lambda}(A^{\nu})\underline{\omega}^{\lambda} \tag{4.122}$$

(In coordinate basis, $\vec{e}_{\lambda}(A^{\nu}) = \frac{\partial}{\partial x^{\lambda}}(A^{\nu}) = A^{\nu}_{,\lambda}$) giving:

$$\underline{d}\vec{A} = \vec{e}_{\nu} \otimes [\vec{e}_{\lambda}(A^{\nu})\underline{\omega}^{\lambda}] + A^{\mu}\Gamma^{\nu}_{\mu\lambda}\vec{e}_{\nu} \otimes \underline{\omega}^{\lambda}
= (\vec{e}_{\lambda}(A^{\nu}) + A^{\mu}\Gamma^{\nu}_{\mu\lambda})\vec{e}_{\nu} \otimes \underline{\omega}^{\lambda}$$
(4.123)

$$\underline{d}\vec{A} = A^{\nu}_{;\lambda}\vec{e}_{\nu} \otimes \underline{\omega}^{\lambda} \tag{4.124}$$

Definition 4.9.2 (Connection forms $\underline{\Omega}^{\nu}_{\mu}$)

The connection forms $\underline{\Omega}^{\nu}_{~\mu}$ are 1-forms, defined by:

$$\underline{d}\vec{e}_{\mu} \equiv \vec{e}_{\nu} \otimes \underline{\Omega}_{\mu}^{\nu}
\Gamma^{\nu}_{\mu\alpha}\vec{e}_{\nu} \otimes \underline{\omega}^{\alpha} = \vec{e}_{\nu} \otimes \Gamma^{\nu}_{\mu\alpha}\underline{\omega}^{\alpha} = \vec{e}_{\nu} \otimes \underline{\Omega}_{\mu}^{\nu}$$
(4.125)

$$\underline{\Omega}^{\nu}_{\ \mu} = \Gamma^{\nu}_{\ \mu\alpha}\underline{\omega}^{\alpha} \tag{4.126}$$

The exterior derivatives of the components of the metric tensor:

$$\underline{d}g_{\mu\nu} = \underline{d}(\vec{e}_{\mu} \cdot \vec{e}_{\nu}) = \vec{e}_{\mu} \cdot \underline{d}\vec{e}_{\nu} + \vec{e}_{\nu} \cdot \underline{d}\vec{e}_{\mu}$$
(4.127)

where the meaning of the dot is defined as follows:

Definition 4.9.3 (Scalar product between vector and 1-form)

The scalar product between a vector \vec{u} and a (vectorial) one form $\underline{A} = A^{\mu}_{\ \nu} \vec{e}_{\mu} \otimes \underline{\omega}^{\nu}$ is defined by:

$$\vec{u} \cdot \underline{A} \equiv u^{\alpha} A^{\mu}_{\ \nu} (\vec{e}_{\alpha} \cdot \vec{e}_{\mu}) \underline{\omega}^{\nu} \tag{4.128}$$

Using this definition, we get:

$$\underline{d}g_{\mu\nu} = (\vec{e}_{\mu} \cdot \vec{e}_{\lambda})\underline{\Omega}^{\lambda}_{\nu} + (\vec{e}_{\nu} \cdot \vec{e}_{\gamma})\underline{\Omega}^{\gamma}_{\mu}
= g_{\mu\lambda}\underline{\Omega}^{\lambda}_{\nu} + g_{\nu\gamma}\underline{\Omega}^{\gamma}_{\mu}$$
(4.129)

Lowering an index gives

$$\underline{d}g_{\mu\nu} = \underline{\Omega}_{\mu\nu} + \underline{\Omega}_{\nu\mu} \tag{4.130}$$

In an orthonormal basis field there is Minkowski-metric:

$$g_{\hat{\mu}\hat{\nu}} = \eta_{\hat{\mu}\hat{\nu}} \tag{4.131}$$

which is constant. Then we have:

$$\underline{d}g_{\hat{\mu}\hat{\nu}} = 0 \Rightarrow \boxed{\underline{\Omega}_{\hat{\nu}\hat{\mu}} = -\underline{\Omega}_{\hat{\mu}\hat{\nu}}} \tag{4.132}$$

where we write $\underline{\Omega}_{\hat{\nu}\hat{\mu}} = \Gamma_{\hat{\nu}\hat{\mu}\hat{\alpha}}\underline{\omega}^{\hat{\alpha}}$. It follows that $\Gamma_{\hat{\nu}\hat{\mu}\hat{\alpha}} = -\Gamma_{\hat{\mu}\hat{\nu}\hat{\alpha}}$. It also follows that

$$\Gamma^{\hat{t}}_{\hat{i}\hat{j}} = -\Gamma_{\hat{t}\hat{i}\hat{j}} = \Gamma_{\hat{i}\hat{t}\hat{j}} = \Gamma^{\hat{i}}_{\hat{t}\hat{j}}
\Gamma^{\hat{i}}_{\hat{j}\hat{k}} = -\Gamma^{\hat{j}}_{\hat{i}\hat{k}}$$
(4.133)