

IN3070/4070 – Logic – Autumn 2019

Lecture 6: Unification, Normal Forms

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Today's Plan

- ▶ Unification
- ▶ Normal Forms
- ▶ Negation Normal Form
- ▶ Conjunctive Normal Form
- ▶ Clausal Form
- ▶ Prenex Normal Forms
- ▶ Skolemization

Outline

- ▶ Unification
- ▶ Normal Forms
- ▶ Negation Normal Form
- ▶ Conjunctive Normal Form
- ▶ Clausal Form
- ▶ Prenex Normal Forms
- ▶ Skolemization

Unification

- ▶ Motivation: try proving the following

$$\forall x p(x, b) \implies \exists y p(a, y)$$

- ▶ Have to “guess” the right instantiations for x and y
- ▶ “make both sides equal”
- ▶ Equation solving with terms!

Unification problem

Let s and t be terms. Find *all* substitutions that make s and t syntactically equal, i.e. all σ with $\sigma(s) = \sigma(t)$.

- ▶ A substitution that makes s and t syntactically equal is called a **unifier** for s and t .
- ▶ Two terms are **unifiable** if they have a unifier.

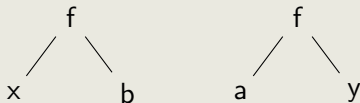
Examples

Are $f(x)$ and $f(a)$ unifiable?

Yes. We see that $\sigma = \{x \setminus a\}$ is a *unifier*: $\sigma(f(x)) = f(a)$

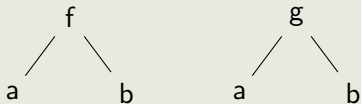
Are $f(x, b)$ and $f(a, y)$ unifiable?

Easier to see if we write terms as *trees*:



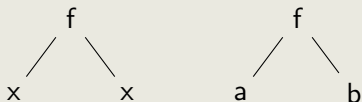
- ▶ The root symbols are the same.
- ▶ The left children are different, but can be unified with $\{x \setminus a\}$.
- ▶ The right children are different, but can be unified with $\{y \setminus b\}$.

Are $f(a, b)$ and $g(a, b)$ unifiable?



- ▶ The root symbols are different, and can *not* be unified!

Are $f(x, x)$ and $f(a, b)$ unifiable?



- ▶ The root symbols are equal.
- ▶ The left children are different, but can be unified with $\{x \setminus a\}$.
- ▶ We must apply $\{x \setminus a\}$ to x in both branches.
- ▶ The right children are now different, and can *not* be unified!

Are x and $f(x)$ unifiable?

x	f
	x

- ▶ The root symbols are different, but can be unified by $\{x \setminus f(x)\}$.
- ▶ We also have to apply $\{x \setminus f(x)\}$ on x in the right tree.
- ▶ The symbols x and f are different.
- ▶ If we unify with $\{f(x)/x\}$, we have to replace x in the right tree again.
- ▶ This continues indefinitely

Unification

Generally:

- ▶ Two *distinct* constant or function symbols are **not** unifiable.
- ▶ A variable x is **not** unifiable with a term that *contains* x .

- ▶ We will define a **unification algorithm**, that finds **all** unifiers for two terms.
- ▶ Problem: Two terms can potentially have infinitely many unifiers. We can't compute all of them!
- ▶ Solution: Find a **representative** σ for the set of unifiers, such that all other unifiers can be constructed from σ .
- ▶ Such a unifier is known as a **most general unifier**.

Composition of Substitutions

- ▶ Let σ and τ be substitutions.
- ▶ Assume we apply first σ and then τ to a term t : $\tau(\sigma(t))$.
- ▶ The effect of this is also a substitution.

Definition 1.1 (Composition of Substitutions).

Let σ and τ be substitutions. The *composition* of σ and τ is a substitution written $\tau\sigma$, such that $(\tau\sigma)(x) = \tau(\sigma(x))$ for all variables x .

- ▶ Exercise: show that $(\tau\sigma)(A) = \tau(\sigma(A))$ for all formulae A and all substitutions σ and τ .

Composition of Substitutions with finite support

Proposition 1.1.

Let $\sigma = \{x_1 \setminus s_1, \dots, x_n \setminus s_n\}$ and $\tau = \{y_1 \setminus t_1, \dots, y_k \setminus t_k\}$. Then

$$\tau\sigma = \{x_1 \setminus \tau(s_1), \dots, x_n \setminus \tau(s_n), z_1 \setminus \tau(z_1), \dots, z_m \setminus \tau(z_m)\}$$

where z_1, \dots, z_m are the variables amongst y_1, \dots, y_k that are **not** amongst x_1, \dots, x_n .

Let $\sigma = \{x \setminus z, y \setminus a\}$ and $\tau = \{y \setminus b, z \setminus a\}$.

Then $\tau\sigma = \{x \setminus \tau(z), y \setminus \tau(a), z \setminus \tau(z)\} = \{x \setminus a, y \setminus a, z \setminus a\}$.

Let $\sigma = \{x \setminus y\}$ and $\tau = \{y \setminus x\}$.

Then $\tau\sigma = \{x \setminus \tau(y), y \setminus \tau(y)\} = \{x \setminus x, y \setminus x\} = \{y \setminus x\}$.

More General Substitution

Definition 1.2 (More General Substitution).

Let σ_1 and σ_2 be substitutions. We say that σ_2 is *more general* than σ_1 if there exists a substitution τ such that $\sigma_1 = \tau\sigma_2$.

Is $\{x \setminus f(y)\}$ more general than $\{x \setminus f(a), y \setminus a\}$?

Yes, since $\{x \setminus f(a), y \setminus a\} = \{y \setminus a\}\{x \setminus f(y)\}$.

Is $\{x \setminus f(a)\}$ more general than $\{x \setminus f(y)\}$?

No, because there is no substitution τ such that $\{x \setminus f(y)\} = \tau\{x \setminus f(a)\}$.

Is $\{x \setminus f(y)\}$ more general than $\{x \setminus f(y)\}$?

Yes, since $\{x \setminus f(y)\} = \{\}\{x \setminus f(y)\}$, where $\{\}$ is the identity substitution.

Most General Unifiers

Definition 1.3 (Unifier, Most General Unifier).

Let s and t be terms. A substitution σ is

- ▶ a **unifier** for s and t if $\sigma(s) = \sigma(t)$.
- ▶ a **most general unifier** (mgu) for s and t if
 - ▶ it is a unifier for s and t , and
 - ▶ it is more general than any other unifiers for s and t .

We say that s and t are **unifiable** if they have a unifier.

Let $s = f(x)$ and $t = f(y)$.

- ▶ $\sigma_1 = \{x \setminus a, y \setminus a\}$ is a unifier for s and t
- ▶ $\sigma_2 = \{x \setminus y\}$ and $\sigma_3 = \{y \setminus x\}$ are also unifiers for s and t
- ▶ σ_2 and σ_3 are the most general unifiers for s and t

Variable Renaming

- ▶ The previous example shows that two terms can have several most general unifiers.
- ▶ But these mgus are always equal **up to variable renaming**.

Definition 1.4 (Variable Renaming).

A substitution η is a **variable renaming** if

1. $\eta(x)$ is a variable for all $x \in \mathcal{V}$, and
2. $\eta(x) \neq \eta(y)$ for all $x, y \in \mathcal{V}$ with $x \neq y$.

Are these substitutions variable renamings?

- ▶ $\sigma_1 = \{x \setminus z, y \setminus x, z \setminus y\}$ Yes.
- ▶ $\sigma_2 = \{x \setminus z, z \setminus y\}$ No, because $\sigma_2(y) = \sigma_2(z)$.
- ▶ $\sigma_3 = \{x \setminus z, y \setminus x, z \setminus y, u \setminus a\}$ No, because $\sigma_3(u)$ is not a variable.

Uniqueness “up to variable renaming”

Proposition 1.2.

If σ_1 and σ_2 are most general unifiers for two terms s and t , then there is a variable renaming η such that $\eta\sigma_1 = \sigma_2$.

- ▶ We leave out the proof.

Subterms

Definition 1.5.

The set of *subterms* of a term t is the smallest set T such that

- ▶ $t \in T$, and
- ▶ if $f(t_1, \dots, t_n) \in T$, then all $t_i \in T$.

All terms in T except t are called *strict subterms* of t .

Let $s = gx$.

- ▶ Subterms: x, gx
- ▶ Strict subterms: x

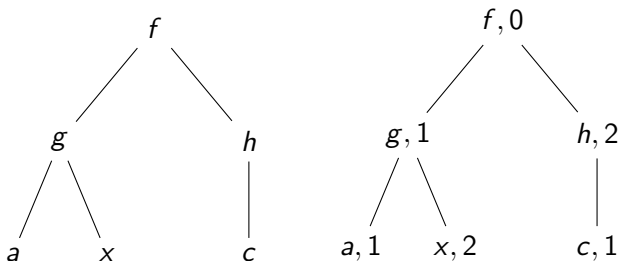
Let $t = f(x, a)$.

- ▶ Subterms: $x, a, f(x, a)$
- ▶ Strict subterms: x, a

- ▶ So every term is a subterm of itself, but not a strict subterm.

Numbered Term Trees

- ▶ We have seen that terms can be represented by trees.
- ▶ For the unification algorithm, it is convenient to number the children of nodes:



- ▶ We call such trees **numbered term trees**.
- ▶ We write the root of the numbered term tree of t as $\text{root}(t)$.

Critical Pair

- ▶ When we unify terms t_1 and t_2 , we want to find subtrees that are **different**.
- ▶ We also want to find differing subtrees as close to the root as possible.

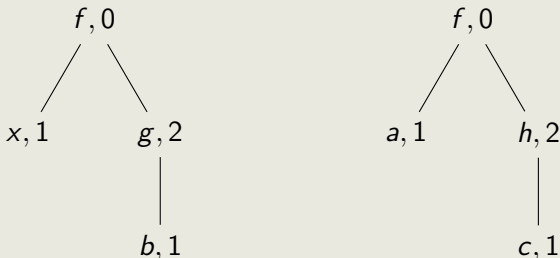
Definition 1.6 (Critical Pairs).

A **critical pair** for two terms t_1 and t_2 is a pair $\langle k_1, k_2 \rangle$ such that

- ▶ k_1 is a subterm of t_1
- ▶ k_2 is a subterm of t_2
- ▶ when terms are considered as numbered trees,
 - ▶ $\text{root}(k_1)$ is different from $\text{root}(k_2)$
 - ▶ The path from $\text{root}(t_1)$ to $\text{root}(k_1)$ is **equal** to the path from $\text{root}(t_2)$ to $\text{root}(k_2)$
- ▶ Paths can be empty, i.e. terms differ at the root.

Example.

Let $s = f(x, gb)$ and $t = f(a, hc)$. This gives the following numbered term trees:



- ▶ Is $\langle b, c \rangle$ a critical pair for s and t ?
 - ▶ No, the path from $\text{root}(s)$ to $\text{root}(b)$ differs from the path from $\text{root}(t)$ to $\text{root}(c)$.
- ▶ Is $\langle x, a \rangle$ a critical pair for s and t ? *Yes.*
- ▶ Is $\langle gb, hc \rangle$ a critical pair for s and t ? *Yes.*

Unification Algorithm

Algorithm: $\text{unify}(t_1, t_2)$

$\sigma := \epsilon;$

while $(\sigma(t_1) \neq \sigma(t_2))$ **do**

 choose a critical pair $\langle k_1, k_2 \rangle$ for $\sigma(t_1), \sigma(t_2)$;

if (neither k_1 nor k_2 are variables) **then**

 return “*not unifiable*”;

end if

$x :=$ the one of k_1, k_2 that is a variable (if both are, choose one)

$t :=$ the one of k_1, k_2 that is not x ;

if (x occurs in t) **then**

 return “*not unifiable*”;

end if

$\sigma := \{x \setminus t\}\sigma;$

end while

return σ ;

Properties of the Unification Algorithm

- ▶ If the terms t_1 and t_2 are unifiable, the algorithm returns a most general unifier for t_1 and t_2 .
- ▶ The mgu is representative for all other unifiers of t_1 and t_2 .
- ▶ If t_1 and t_2 are **not** unifiable, the algorithm returns “*not unifiable*”.

Outline

- ▶ Unification
- ▶ **Normal Forms**
- ▶ Negation Normal Form
- ▶ Conjunctive Normal Form
- ▶ Clausal Form
- ▶ Prenex Normal Forms
- ▶ Skolemization

What are Normal Forms?

- ▶ Given some set A of formulas, grammars, programs, etc.
- ▶ And a subset $N \subseteq A$ that is 'nice'
 - ▶ Easy to read off certain properties
 - ▶ Easy to compute with
 - ▶ Easy to write programs for
 - ▶ ...
- ▶ Given an equivalence relation \approx on A
 - ▶ formulas are logically equivalent
 - ▶ grammars describe the same language
 - ▶ programs compute the same function
 - ▶ ...
- ▶ Now assume that for every $a \in A$ there is a $n \in N$ with $n \approx a$.
- ▶ Instead of the 'ugly' a , we can work with the 'nice' n .
- ▶ In computer science: computable function $f : A \rightarrow N$ with $f(a) \approx a$
- ▶ Members of N are "in N -normal form"
- ▶ For every a , we can compute the (or a) N -normal form $f(a)$.

Example: Normal Form for Rational Numbers

- ▶ Let Q be the set of pairs $\langle m, n \rangle$, where we think of $\frac{m}{n}$
- ▶ ‘nice’ fractions are reduced, i.e. no common divisors in m and n
- ▶ E.g. $\frac{3}{4}$ is reduced but $\frac{6}{8}$ is not.
- ▶ Let $\langle m, n \rangle \approx \langle m', n' \rangle$ iff $m \cdot n' = m' \cdot n$, e.g. $\frac{3}{4} \approx \frac{6}{8}$.
- ▶ Reduced fractions are nice to check whether two are \approx : If $\langle m, n \rangle$ and $\langle m', n' \rangle$ are both reduced, then

$$\langle m, n \rangle \approx \langle m', n' \rangle \quad \Leftrightarrow \quad \langle m, n \rangle = \langle m', n' \rangle$$

- ▶ Algorithm: Given $\langle m, n \rangle$, compute $k = \gcd(m, n)$, return $\langle m/k, n/k \rangle$.
- ▶ Then $\langle m/k, n/k \rangle$ is reduced and $\langle m/k, n/k \rangle \approx \langle m, n \rangle$
- ▶ So $\langle m/k, n/k \rangle$ is the “reduced normal form” of $\langle m, n \rangle$

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Negation Normal Form

Definition 3.1 (Negation Normal Form).

A formula is in *negation normal form* (NNF) if it contains no implications, and all negations are in front of literals.

Example.

- ▶ $p \rightarrow q$ is not in NNF
- ▶ $\neg p \vee q$ is in NNF
- ▶ $\neg(p \vee \forall x \neg q(x))$ is not in NNF
- ▶ $\neg p \wedge \exists x q(x)$ is in NNF

Theorem 3.1.

Every formula in first-order logic can be transformed into an equivalent formula in NNF.

Proof.

To convert an arbitrary formula to a formula in NNF, remove implications, and push negations inwards, preserving equivalence, using the following:

$$A \rightarrow B \equiv \neg A \vee B$$

$$\neg(A \wedge B) \equiv \neg A \vee \neg B$$

$$\neg(A \vee B) \equiv \neg A \wedge \neg B$$

$$\neg(\forall x A) \equiv \exists x \neg A$$

$$\neg(\exists x A) \equiv \forall x \neg A$$

$$\neg(\neg A) \equiv A$$



Advantage of Negation Normal Form

- ▶ Tableau or single-sided sequent calculi need 50% fewer rules
- ▶ No need to handle negation outside of axioms
- ▶ Sound and complete calculus for propositional logic:

$$\frac{\Gamma, A, B \Rightarrow}{\Gamma, A \wedge B \Rightarrow} \wedge\text{-left} \qquad \frac{\Gamma, A \Rightarrow \quad \Gamma, B \Rightarrow}{\Gamma, A \vee B \Rightarrow} \vee\text{-left}$$

$$\frac{}{\Gamma, A, \neg A \Rightarrow} \text{ax}$$

- ▶ Soundness and completeness proofs also have fewer cases.

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Conjunctive Normal Form

Definition 4.1 (Conjunctive Normal Form).

A formula is in *conjunctive normal form* (CNF) if it is a conjunction of disjunctions of literals.

Example.

$(p \vee \neg q) \wedge (\neg p \vee q)$ is in CNF.

$(p \vee \neg q) \wedge (\neg p \vee (q \wedge q))$ is *not* in CNF.

What about just p or $(p \vee q)$? Yes, if we consider a literal to be both a conjunction and a disjunction.

Theorem 4.1.

Every formula in *propositional* logic can be transformed into an equivalent formula in CNF.

Proof.

To convert an arbitrary propositional formula to a formula in CNF perform the following steps, each of which preserves logical equivalence:

- (1) Convert to negation normal form.
- (2) Use the distributive laws to move conjunctions inside disjunctions to the outside

$$A \vee (B \wedge C) \equiv (A \vee B) \wedge (A \vee C)$$



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Clausal Form

Definition 5.1 (Clausal Form).

A *clause* is a set of literals. A clause is considered to be an implicit disjunction of its literals. A *unit clause* is a clause consisting of exactly one literal. The empty set of literals is the *empty clause*, denoted by \square . A formula in *clausal form* is a set of clauses. A formula is considered to be an implicit conjunction of its clauses. The formula that is the *empty set of clauses* is denoted by \emptyset .

The only significant difference between clausal form and the standard syntax is that clausal form is defined in terms of sets.

$(p \vee \neg q) \wedge (\neg p \vee q)$ in clausal form: $\{\{p, \neg q\}, \{\neg p, q\}\}$

Transformation to Clausal Form

Corollary 5.1.

Every formula ϕ in propositional logic can be transformed into an logically equivalent formula in clausal form.

Proof.

This follows from the previous theorem, where we transformed a formula to CNF. Each disjunction is then transformed to a clause (of literals), and the clausal form is the set of these clauses. □

Empty Clause and Empty Set of Clauses

Lemma 5.1.

\square , the empty clause, is unsatisfiable.

\emptyset , the empty set of clauses, is valid.

Proof.

A clause is satisfiable iff there is **some** interpretation under which **at least one literal** in the clause is true. Let \mathcal{I} be an arbitrary interpretation. Since there are no literals in \square , there are **no** literals whose value is true under \mathcal{I} . But \mathcal{I} was an arbitrary interpretation, so \square is unsatisfiable.

A set of clauses is valid iff **every** clause in the set is true in every interpretation. But there are no clauses in \emptyset that need be true, so \emptyset is valid. □

Short Hand Notation for Clauses

Notation

- ▶ $\{pr, \bar{q}\bar{p}q, p\bar{p}q\}$ means $(p \vee r) \wedge (\neg q \vee \neg p \vee q) \wedge (p \vee \neg p \vee q)$.
- ▶ S usually denotes a formula in clausal form.
- ▶ C usually denotes a clause.
- ▶ l usually denotes a literal.
- ▶ l^c then represents its *complement*.

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Prenex Conjunctive Normal Form

Definition 6.1 (Prenex Conjunctive Normal Form).

A formula is in *prenex conjunctive normal form* (PCNF) iff it is of the form:

$$Q_1x_1 \cdots Q_nx_nM$$

where the Q_i are quantifiers (\forall/\exists) and M is a quantifier-free formula in CNF. The sequence $Q_1x_1 \cdots Q_nx_n$ is the *prefix* and M is the *matrix*.

Example.

$\forall x\forall y((p(x,y) \vee \neg p(y,x)) \wedge (q(x,y) \vee \neg q(y,x)))$ is in PCNF.

$\forall x(\neg p(x) \vee \exists yq(y))$ is *not* in PCNF.

Clausal Form for First-order Formulae

Definition 6.2 (Clausal Form).

Let A be a closed formula in PCNF whose prefix consists only of universal quantifiers. The *clausal form* of A consists of the matrix of A written as a set of clauses.

Example.

$$\forall x \forall y ((p(x, y) \vee \neg p(y, x)) \wedge (q(x, y) \vee \neg q(y, x)))$$

can be written in clausal form as

$$\{\{p(x, y), \neg p(y, x)\}, \{q(x, y), \neg q(y, x)\}\}$$

Note: The universal quantifiers are implicit.

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Skolem's Theorem

Theorem 7.1 (Skolem).

There is an algorithm that for any closed formula A computes a formula A' in clausal form such that $A \approx A'$.

The notation $A \approx A'$ means that A is satisfiable if and only if A' is satisfiable. This is **not** the same as logical equivalence. We call it **equisatisfiability**.

Named after the Norwegian mathematician and logician **Thoralf Albert Skolem** (1887–1963).

“Satisfiability is more interesting than validity. Always true or always false are extremes.”

Skolem's Algorithm

Algorithm for obtaining A' :

- ▶ Rename bound variables so that no variable appears in two quantifiers.
- ▶ Transform to negation normal form
- ▶ Extract quantifiers from the matrix until all quantifiers appear in the prefix and the matrix is quantifier-free.

$$A \wedge \forall x B \equiv \forall x(A \wedge B) \quad \text{if } x \text{ not free in } A$$

$$A \wedge \exists x B \equiv \exists x(A \wedge B) \quad \text{if } x \text{ not free in } A$$

$$A \vee \forall x B \equiv \forall x(A \vee B) \quad \text{if } x \text{ not free in } A$$

$$A \vee \exists x B \equiv \exists x(A \vee B) \quad \text{if } x \text{ not free in } A$$

- ▶ Use the distributive laws to transform the matrix into CNF.
- ▶ The formula is now in PCNF.

Skolem's Algorithm (cont.)

Algorithm for obtaining A' (continued):

- ▶ For every existential quantifier $\exists x$ in the prefix, let y_1, \dots, y_n be the universally quantified variables **preceding** $\exists x$ and let f be a **new** n -ary function symbol.
- ▶ Delete $\exists x$ and replace every occurrence of x by $f(y_1, \dots, y_n)$.
- ▶ If there are no universal quantifiers preceding $\exists x$, replace x by a new constant (0-ary function).
- ▶ These new function symbols are **Skolem functions** and the process of replacing existential quantifiers by functions is **Skolemization**.

Skolemization Example

Example.

- ▶ Look at the formulas $\forall x \exists y p(x, y)$ and $\forall x p(x, f(x))$.
- ▶ Are they *equivalent*? No!
- ▶ Are they *equisatisfiable*? Yes!
- ▶ The Skolemization of $\forall x \exists y p(x, y)$ is $\forall x p(x, f(x))$, and if one of them has a model, so does the other.

Proof of Skolem's Theorem

- ▶ The first transformations of the algorithm (into PCNF) preserve equivalence.
- ▶ We need to consider the replacement of an existential quantifier by a Skolem function.
- ▶ Suppose that $\mathcal{I} \models \forall y_1 \cdots \forall y_n \exists x A$ for $\mathcal{I} = (D, \iota)$.
- ▶ We must show that there is an interpretation \mathcal{I}' such that $\mathcal{I}' \models \forall y_1 \cdots \forall y_n A[x \setminus f(y_1, \dots, y_n)]$.
- ▶ Let $\mathcal{I}' = (D, \iota')$ such that ι' extends ι with the interpretation of f .
- ▶ Remember that f does not occur in A , so f^ι does not matter
- ▶ For any choice of elements d_1, \dots, d_n from D , there is an element d_{n+1} in D such that

$$v_{\mathcal{I}}(\alpha\{y_1 \leftarrow d_1\} \cdots \{y_n \leftarrow d_n\} \{y_{n+1} \leftarrow d_{n+1}\}, A) = T$$

- ▶ Let $f^{\iota'}(d_1, \dots, d_n) = d_{n+1}$. This ensures that the claim holds.

Example

- ▶ Clause form of $\neg\exists x(p(x) \rightarrow \forall y p(y))$

Outlook

- ▶ We have seen the LK calculus for propositional and first-order logic
- ▶ Sound and complete, but not machine-oriented
- ▶ Machine-oriented calculi use:
 - ▶ Unification to find the right instantiations
 - ▶ Normal forms to simplify reasoning steps
- ▶ Free variable calculi
 - ▶ Similar to LK, but with unification
 - ▶ Often used with NNF or clause form
- ▶ Resolution
 - ▶ Basis of many theorem provers, uses unification
 - ▶ Almost always on clause form