
INF 5300 – Lab exercises on segmentation

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- Snakes
- Mean shift clustering
- Markov random field classification using the ICM algorithm

Lab 11.3.15

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Matlab exercise - Snakes

- The Matlab scripts and images used can be found on the course web page.
- <http://heim.ifi.uio.no/~inf5300/2008/defcont.zip>
- The Gradient vector flow requires functions GVF.m and BoundMirror*.m, found in ~inf5300/www_docs/data

- Start by clearing the workspace and closing all windows. Load a test image.
- Uncomment the test image you want to use.

```
% Start at scratch
% Define external force field
% Read test image and convert to double
```

```
F=imread('circ.tif','tif');
F=double(F);
```

```
% F=imread('square.tif','tif');
% F=double(F);
```

```
%F=imread('u.tif','tif');
%F=double(F);
```

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Matlab demonstration

```
% Display it
```

```
figure
imshow(F,[]);
title('Input image');
```

```
% We want to use the negative magnitude of the gradient of this image as external
% force field so we need sobel masks
```

```
s_vert=-fspecial('sobel');
s_horz=s_vert';
```

```
% Calculate the gradient information.
```

```
F_vert=imfilter(F,s_vert,'replicate');
F_horz=imfilter(F,s_horz,'replicate');
```

```
% Lets look at these two images
```

```
figure
imshow(F_vert,[])
title('Vertical gradients')
figure
imshow(F_horz,[])
title('Horizontal gradients')
```

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Matlab demonstration

```
% Now lets calculate the negative magnitude of the gradient.
% This will be the external force field. In order to allow for
% different input images we normalize the gradient image
% to 1
```

```
P=sqrt(F_horz.*F_horz+F_vert.*F_vert);
P=P/(max(max(P)));
P=-P;
figure
imshow(P,[])
title('Inverse magnitude of gradient vector')
```

```
% Last thing, we need the two spatial derivatives
% of our external force field. Calculate these and
% have a look at them.
```

```
P_vert=imfilter(P,s_vert,'replicate');
P_horz=imfilter(P,s_horz,'replicate');
```

```
figure
imshow(P_horz,[])
title('X derivative of force field')
figure
imshow(P_vert,[])
title('Y derivative of force field')
```

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Take a look at the gradient vectors

```
% Lets take a look at these gradient vectors
%
[X,Y]=meshgrid([1 4:4:256],[1 4:4:256]);
figure
contour(flipud(P))
hold on
quiver(X,flipud(Y),getmatind(-
P_horz,X,Y),getmatind(P_vert,X,Y))
axis image
title('Gradient vectors and contour lines')
```

- Note that close to the border (where the gradient is non-zero), the gradient vector points in the direction of the maximum gradient.
- Acting like a force for the snake this will pull the snake in the direction of the maximum gradient

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Matlab demonstration

```
% Now lets define our snake, to begin with lets decide
% on some small number of control points (you can change
% this to your liking, the rest of the program will adapt
% gracefully)
```

```
N=20;
```

```
% Now we need to give the snake a shape. Lets make it a circle
% and then "nudge" it a little.
```

```
x0=50*cos(0:(2*pi/(N)):(2*pi-(2*pi/(N))))+128
y0=-50*sin(0:(2*pi/(N)):(2*pi-(2*pi/(N))))+128
```

```
x0(2)=x0(2)+30;
y0(2)=y0(2)-20;
```

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Matlab demonstration

```
% Define the weights given to the two terms in the inner energy
% functional. The values are NOT arbitrary.
```

```
w1=0.000001;
w2=0.01;
```

```
% Define constants for the stiffness matrix, do not edit this.
```

```
alpha=w2;
beta=-w1-4*w2;
gamma=-2*w1+6*w2;
```

```
% Define the step size
```

```
lambda = 0.2 % Stiff system
% lambda=0.1; % Unstiff system
```

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Matlab demonstration

```
% Define Stiffness matrix. The code below is just a smart way of doing
% this independently of the number of nodes.
```

```
% A=[gamma    beta    alpha    0    0    0    alpha    beta;
%    beta    gamma    beta    alpha    0    0    0    alpha;
%    alpha    beta    gamma    beta    alpha    0    0    0;
%    0    alpha    beta    gamma    beta    alpha    0    0;
%    0    0    alpha    beta    gamma    beta    alpha    0;
%    0    0    0    alpha    beta    gamma    beta    alpha;
%    alpha    0    0    0    alpha    beta    gamma    beta;
%    beta    alpha    0    0    0    alpha    beta    gamma];
```

```
A=diag(beta,-N+1)+...
diag(alpha*ones(1,2),-N+2)+...
diag(alpha*ones(1,N-2),-2)+...
diag(beta*ones(1,N-1),-1)+...
diag(gamma*ones(1,N),0)+...
diag(beta*ones(1,N-1),+1)+...
diag(alpha*ones(1,N-2),2)+...
diag(alpha*ones(1,2),N-2)+...
diag(beta,N-1)
```

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Matlab demonstration

```
% Initialise x and y

x=x0';
y=y0';

% The maximum number of iterations

maxiter=500;

% Weight given to external field, set to 0 or 1.

omega=1; %How much should the gradient information be weighed?

% Display results on top of the input image

figure
imshow(P,[])
title('Snake position')
hold on
```

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Matlab demonstration

```
iter=0;
while(iter<maxiter)
    c=rand(1,3); % Randomly color the snake
    %plot(x,y,'*', 'color',c) % Plot the snake control points
    lplot(x,y,c) % Interconnect the nodes
    iter=iter+1 % Display the iteration number
    x=(inv(A+lambda*eye(N)))*(lambda*x-
        omega*getmatind(P_horz,round(x)+1,round(y)+1));
    y=(inv(A+lambda*eye(N)))*(lambda*y-
        omega*getmatind(P_vert,round(x)+1,round(y)+1));
    dummy=input(['Press return to continue']);
end
```

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Matlab demonstration

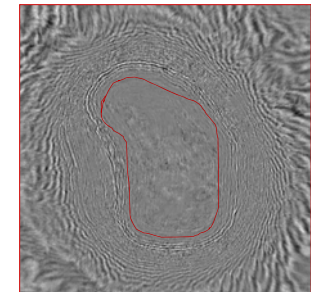
- First, try to run the snake with only internal forces.
- Let's first focus on the "tension force".
- Initialize to a circle.
- Set the weight for the external force (omega) to zero.
- What happens?

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A more difficult example

- Try the snake on this image
~inf5300/www_docs/data/seismic_timeslice.mat
The boundary we are looking for is the texture boundary between the high-frequency texture, and the homogeneous inside.
First – find a feature that has high gradient close to this boundary and low gradient elsewhere.
Use this feature image as input to the snake.
Initialize the snake using a circle both inside and outside the true contour.
Can you make it work?



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