

The Compulsory problem sets are now available at 7th floor of the Math. Building (the "Oldig Shelves").

(Contact me if you should be missing)

A more general Maximum Principle.

We shall next study control problems of the following type:

$$(*) \begin{cases} \max \int_{t_0}^{t_1} f(t, x(t), u(t)) dt \\ \dot{x}(t) = g(t, x(t), u(t)), \quad x_0 = x(t_0) \text{ given, } u(t) \in U, (t \in [t_0, t_1]), \\ \text{where } [t_0, t_1] \text{ is a given interval in } \mathbb{R}, \end{cases}$$

We assume that  $f$  and  $g$  are  $C^1$ -functions (real valued).

Moreover, we suppose that  $x(t_1)$  satisfies exactly one of the following 3 conditions:

- (i)  $x(t_1) = X_1$ ,  $X_1$  a given real value (fixed)
- (ii)  $x(t_1) \geq X_1$ , — — — — — (condition on  $x(t_1)$ )
- (iii)  $x(t_1)$  is free (no condition on  $x(t_1)$ )

In order that the Maximum Principle shall hold, it now becomes necessary to consider the following two possibilities for the Hamiltonian  $H$ :

$$(A) \quad H(t, x, u, p) = f(t, x, u) + p g(t, x, u) \quad (\text{Normal problems})$$

$$(B) \quad H(t, x, u, p) = p g(t, x, u) \quad (\text{Non-normal or degenerate problems})$$

(A) and (B) may be written in one formula:

$$H(t, x, u, p) = p_0 f(t, x, u) + p g(t, x, u)$$

where  $p_0 = 1$  or  $p_0 = 0$

Remark. If  $x(t_1)$  is free (case (iii) above), then the problem will always be normal

More generally, the problem is always normal if  $p(t) = 0$  for some  $t \in [t_0, t_1]$  ( $p$  is the adjoint function of the problem, given in the Maximum Principle, see below).

## The Maximum Principle II (general version)

Suppose that  $(x^*, u^*)$  is an optimal pair for the problem  $(\mathcal{P})$  with exactly one of the terminal conditions (i), (ii), (iii) satisfied.

Then there is a continuous, piecewise differentiable function  $p$  (called the adjoint function of the problem) such that  $p(t_1)$  satisfies exactly one of the following transversality conditions:

- (i) no condition on  $p(t_1)$  if (i)  $x(t_1) = x_1$   
 if (ii)  $x(t_1) \geq x_1$  ( $p(t_1) = 0$  if  $x(t_1) > x_1$ )  
 (ii')  $p(t_1) \geq 0$   
 (iii')  $p(t_1) = 0$  if (iii)  $x(t_1)$  is free

In addition, for each  $t \in [t_0, t_1]$ , we must have

(a)  $u = u^*(t)$  maximizes the function  $h_t$ , where  
 $h_t(u) = H(t, x^*(t), u, p(t))$ , for  $u \in U$  (the control region)

(b)  $\frac{\partial H^*}{\partial x} = -\dot{p}(t)$  (where  $\frac{\partial H^*}{\partial x} = \frac{\partial H}{\partial x}(t, x^*(t), u^*(t), p(t))$ )

except at the discontinuities of  $u^*$ .

[ (c) If  $p(t_1) = 0$  for some  $t \in [t_0, t_1]$ , then the problem is normal.]  
 As before we also have the following sufficient condition for a maximum:

### Mangasarian's Theorem

Suppose that  $(x^*, u^*)$  is an admissible pair for the problem  $(\mathcal{P})$  that satisfies all the conditions of the Maximum Principle. If for each  $t \in [t_0, t_1]$ , the function

$(x, u) \mapsto H(t, x, u, p(t))$  is concave, then

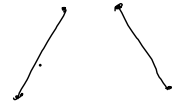
$(x^*, u^*)$  is an optimal pair for the problem

(that is,  $(x^*, u^*)$  maximizes the integral in  $(\mathcal{P})$ )

Example 3. Solve (the normal problem)

$$\max_u \int_0^1 x(t) dt, \quad \dot{x} = x + u, \quad x(0) = 0, \quad x(1) \geq 1$$

$$u(t) = [-1, 1] = \mathcal{U}$$



Solution. Since we assume that the problem is normal,

$$H(t, x, u, p) = x + p(x+u) = (1+p)x + pu,$$

which is linear (of first degree) in  $(x, u)$ , hence

$(x, u) \mapsto H(t, x, u, p(t))$  is both concave and convex. Therefore, Mangasarian's Theorem applies. Here we must have:

$$(i) \quad p(1) \geq 0 \quad [p(1) = 0 \text{ if } x(1) > 1]$$

$H$  is maximized as a function of  $u$  at one of the endpoints  $u=1$  or  $u=-1$  (since  $u$  is linear).

$$\text{Hence } u^*(t) = \begin{cases} 1, & \text{if } p(t) > 0 \\ -1, & \text{if } p(t) < 0 \\ \text{can be chosen arbitrarily in } [-1, 1], & \text{as } H \text{ is constant in } u \text{ if } p(t) = 0 \end{cases}$$

We choose  $u^*(t) = 1$  in this case

Furthermore, for  $x = x^*$ ,  $u = u^*$ , we must have

$$\frac{\partial H}{\partial x} = 1 + p = -\dot{p} \quad (\text{from (b) of the Max. Principle})$$

$$\text{Hence } \dot{p} + p = -1$$

$$\text{Thus } p(t) = Ae^{-t} - 1,$$

$$\text{where } p(1) = Ae^{-1} - 1 \geq 0 \quad (\text{by the max. principle})$$

$$\text{Hence } Ae^{-1} \geq 1, \quad \underline{A \geq e}$$

$$\text{Then } p(t) = Ae^{-t} - 1 \geq e e^{-t} - 1 = \underline{e^{1-t} - 1} := h(t),$$

$$\text{where } \dot{h}(t) = -e^{1-t} < 0 \quad \text{and } h(1) = e^0 - 1 = 0$$

$$\text{Moreover, } h(0) = e - 1 > 0, \quad t \in [0, 1], \quad \text{so that}$$

$$h(t) \in [0, e-1].$$

$$\text{In particular, } p(t) \geq h(t) > 0, \quad t \in [0, 1), \quad p(1) \geq 0.$$

$$\text{Hence } H \text{ as a function of } u \text{ is increasing, so}$$

$$u = u^*(t) = 1, \quad t \in [0, 1].$$

$$\text{Hence } \dot{x}^* - x^* = 1,$$

$$x^*(t) = Be^t - 1$$

$$x^*(0) = 0 \Rightarrow B = 1 \Rightarrow x^*(t) = \underline{e^t - 1}$$

$$\text{Hence } x^*(1) = e - 1 > 1, \quad \text{so } p(1) = 0, \quad \text{so } A = 1.$$

$$x^*(t) = e^t - 1, \quad u^*(t) = 1, \quad t \in [0, 1],$$

is the optimal pair in light of Mangasarian's Theorem.

Example 4. Solve the (normal) problem:

$$\max \int_0^1 (2x - x^2) dt, \quad \dot{x} = u, \quad x(0) = x(1) = 0, \quad -1 \leq u(t) \leq 1$$

Solution.

Here  $H(t, x, u, p) = 2x - x^2 + pu$  (By the "2nd derivative test")

is concave in  $(x, u)$ :

$$\frac{\partial^2 H}{\partial x^2} = -2 \leq 0, \quad \frac{\partial^2 H}{\partial u^2} = 0 \leq 0, \quad \frac{\partial^2 H}{\partial x \partial u} = 0,$$

$$\Delta_H = \begin{vmatrix} \frac{\partial^2 H}{\partial x^2} & \frac{\partial^2 H}{\partial x \partial u} \\ \frac{\partial^2 H}{\partial x \partial u} & \frac{\partial^2 H}{\partial u^2} \end{vmatrix} = (-2) \cdot 0 - 0^2 = 0 \geq 0$$

Mangasarian's Thm. therefore applies.

$H$  is linear in  $u$  so the maximum of  $H$  occurs at an endpoint  $u = -1, u = 1$ . Hence, for any optimal pair  $(x^*, u^*)$  we have

$$u^*(t) = \begin{cases} 1, & \text{if } p(t) \geq 0 \\ -1, & \text{if } p(t) < 0 \end{cases} \quad (\text{choosing } u^* = 1 \text{ if } p(t) = 0)$$

Furthermore,

$$\dot{p}(t) = -\frac{\partial H^*}{\partial x} = -(2 - 2x^*(t)) = -2 + 2x^*(t)$$

Since  $x^*(0) = 0$  and  $\dot{x}^* = u^* \leq 1$ , so  $\int_0^t \dot{x}^*(s) ds = x^*(t) - x^*(0) = x^*(t) \leq \int_0^t 1 ds = t \leq 1$   
 so that  $x^*(t) < 1, t \in [0, 1)$ .

Hence  $\dot{p}(t) = 2(x^*(t) - 1) < 0, t \in [0, 1)$

so  $p$  is strictly decreasing on  $[0, 1)$ .

Next, if we consider the following possibilities:

(1)  $p(0) \leq 0$ , then  $p(t) < 0$  on  $[0, 1]$ , then  $u^*(t) = -1$  on  $(0, 1]$ ,

hence  $\dot{x}^* = -1$ , so  $x^*(t) = -t$  on  $(0, 1]$ .

Impossible since  $x^*(1) = 0$ !

(2)  $p(1) \geq 0$ , then  $p(t) > 0$  on  $[0, 1)$  ( $p$  was strictly decreasing on  $(0, 1)$ ),  
 hence  $u^* = \dot{x}^* = 1$ , so  $x^*(t) = t$ , impossible as  $x^*(1) = 0$ .

Hence  $p(0) > 0$  and  $p(1) < 0$

Thm.  $p$  is strictly decreasing on  $[0, 1)$ , so there is a unique  $t_0$  on  $(0, 1)$  such that  $p(t_0) = 0$ .

Hence

$$x^*(t) = u^*(t) = \begin{cases} 1, & t \in [0, t_0) \\ -1, & t \in (t_0, 1] \\ \text{undetermined if } t = t_0 \end{cases}$$

As  $x^*(0) = 0$ , we have  $x^*(t) = t, t \in [0, t_0)$

and since  $x^*(1) = 0$ , we have

$$x^*(t) = -t + 1, t \in (t_0, 1]$$

Since  $x^*$  is continuous at  $t_0$ , we have

$$t_0 = \lim_{t \rightarrow t_0^-} x^*(t) = \lim_{t \rightarrow t_0^+} x^*(t) = -t_0 + 1$$

Hence  $t_0 = \frac{1}{2}$

Then we know  $u^*(t)$  and  $x^*(t)$

This is an optimal pair Mangasarian's Thm.

