

SET 7 (March 9, 2016) MAT 2440IP 5.1 (8)

(1) $x'' + 3x' + 4x - 2y = 0$

(2) $y'' + 2y' - 3x + y = \cos t$

To transform into 1st order linear system:

Let

$$x_1 = x, \quad x_2 = x_1' = x' \quad (\text{then } x_2' = x'')$$

$$y_1 = y, \quad y_2 = y_1' = y' \quad (\text{so } y_2' = y'')$$

Get:

$$\begin{cases} x_1' = x_2 \\ x_2' + 3x_1' + 4x_1 - 2y_1 = 0 \\ y_1' = y_2 \\ y_2' + 2y_1' - 3x_1 + y_1 = \cos t \end{cases}$$

or

$$\begin{cases} x_1' = x_2 \\ x_2' = -4x_1 - 3x_2 + 2y_1 \\ y_1' = y_2 \\ y_2' = 3x_1 - y_1 - 2y_2 + \cos t \end{cases}$$

or in matrix form

$$\begin{bmatrix} x_1' \\ x_2' \\ y_1' \\ y_2' \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ -4 & -3 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 3 & 0 & -1 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ y_1 \\ y_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 0 \\ \cos t \end{bmatrix}$$

Not required for the problem :

Eigenvalues of matrix

$$|\lambda I - P| = 0, \text{ get } \lambda^4 + 5\lambda^3 + 11\lambda^2 + 5\lambda + 4 = 0$$

MATLAB : $A = [0, 1, 0, 0; -4, -3, 2, 0; \dots]$

$$[V, D] = \text{eig}(A)$$

Get

$$\lambda = -0.2911 \pm i0.4931; -2.2089 \pm i1.1049$$

Control :

$$\prod_{k=1}^4 \lambda_k = 4, \quad \sum_{k=1}^4 \lambda_k = -5 \quad \underline{\underline{OK}}$$

Eigenvectors :

$$\vec{v}_1 = \begin{bmatrix} -0.4269 + i0.1715 \\ 0.0397 - i0.2604 \\ -0.7358 \\ 0.2142 - i0.3629 \end{bmatrix}, \quad \vec{v}_2 = \dots \quad \vec{v}_4 = \dots$$

5.1 (21) a (Cfr. 5.1.11)

$$\begin{aligned} \text{(i)} \quad x' &= y & \begin{bmatrix} x' \\ y' \end{bmatrix} &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \\ \text{(ii)} \quad y' &= -x \end{aligned}$$

By elimination: $x'' + x = 0$: $r = \pm i$,

$$x(t) = A \cos t + B \sin t$$

$$y(t) = -A \sin t + B \cos t$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = A \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + B \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

Hence $\begin{bmatrix} \cos t \\ -\sin t \end{bmatrix}$, $\begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$

are linearly independent vector solutions
They generate the (2-dimensional)
solution space.

Here

$$\begin{aligned} & x(t)^2 + y(t)^2 \\ &= A^2 \cos^2 t + B^2 \sin^2 t + 2AB \sin t \cos t \\ & \quad + A^2 \sin^2 t + B^2 \cos^2 t - 2AB \sin t \cos t \\ &= A^2 \cdot 1 + B^2 \cdot 1 = r^2 \geq 0 \end{aligned}$$

So solution curves are circles centered
at $(0,0)$ with radius $r \geq 0$, $r = \sqrt{A^2 + B^2}$

(b) Consider

$$\begin{aligned} x' &= y \\ y' &= x \end{aligned} \quad \text{or} \quad \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

Elimination:

$$x'' = y' = x, \quad x'' - x = 0$$

$$r = \pm 1,$$

$$x(t) = A e^{-t} + B e^t$$

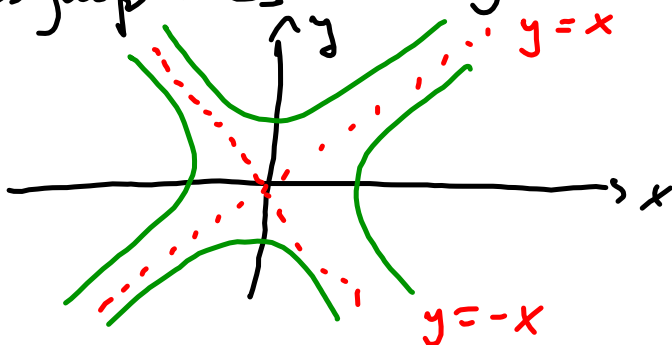
$$y(t) = x'(t) = -A e^{-t} + B e^t$$

$$\begin{aligned} x(t)^2 - y(t)^2 &= A^2 e^{-2t} + B^2 e^{2t} + 2AB \\ &\quad - (A^2 e^{-2t} + B^2 e^{2t} - 2AB) \\ &= 4AB = C = \text{constant.} \end{aligned}$$

Solution curves:

$$(x - y)(x + y) = C,$$

hyperbolas centered at $(0, 0)$, with asymptotes: $y = x$ and $y = -x$



5.3 (21) Given

$$\text{*) } \vec{x}' = \underbrace{\begin{bmatrix} 4 & 2 \\ -3 & -1 \end{bmatrix}}_A \vec{x}, \quad \text{or } \vec{x}' = A\vec{x}$$

Then $\vec{x}_1(t) = \begin{bmatrix} 2e^t \\ -3e^t \end{bmatrix}$ and $\vec{x}_2(t) = \begin{bmatrix} e^{2t} \\ -e^{2t} \end{bmatrix}$
are solutions of (*) :

$$\begin{bmatrix} 4 & 2 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} 2e^t \\ -3e^t \end{bmatrix} = \begin{bmatrix} 2e^t \\ -3e^t \end{bmatrix} = \vec{x}_1(t),$$

and $\vec{x}_1'(t) = \begin{bmatrix} 2e^t \\ -3e^t \end{bmatrix} = \vec{x}_1(t)$

So $\vec{x}_1' = A\vec{x}_1 = \vec{x}_1$ with \vec{x}_1 eigenvector
with $\lambda = 1$ as
eigenvalue

Furthermore,

$$\begin{bmatrix} 4 & 2 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} e^{2t} \\ -e^{2t} \end{bmatrix} = \begin{bmatrix} 2e^{2t} \\ -2e^{2t} \end{bmatrix} = 2 \begin{bmatrix} e^{2t} \\ -e^{2t} \end{bmatrix} = 2\vec{x}_2(t)$$

and

$$\vec{x}_2'(t) = \begin{bmatrix} 2e^{2t} \\ -2e^{2t} \end{bmatrix} = 2\vec{x}_2(t)$$

So \vec{x}_2 is a solution. Observe: \vec{x}_2
is eigenvector with eigenvalue 2
for A. Solution space is $\text{span}\{\vec{x}_1, \vec{x}_2\}$

5.4 (17) "Eigenvalue method" :

$$\left. \begin{aligned} x_1' &= 4x_1 + x_2 + 4x_3 \\ x_2' &= x_1 + 7x_2 + x_3 \\ x_3' &= 4x_1 + x_2 + 4x_3 \end{aligned} \right\} \underbrace{\begin{bmatrix} 4 & 1 & 4 \\ 1 & 7 & 1 \\ 4 & 1 & 4 \end{bmatrix}}_P \underbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} x_1' \\ x_2' \\ x_3' \end{bmatrix}}_{\vec{x}'}$$

or $\vec{x}' = P\vec{x}$

Notice that $\lambda = 0$ is an eigenvalue of P , as 1st and 3rd rows are equal (so $\det(0 \cdot I - P) = \det P = 0$)
Characteristic equation of P :

$$0 = |\lambda I - P| = \begin{vmatrix} \lambda - 4 & -1 & -4 \\ -1 & \lambda - 7 & -1 \\ -4 & -1 & \lambda - 4 \end{vmatrix} \quad (R_3 \rightarrow R_3 - 4R_1)$$

$$= \begin{vmatrix} \lambda - 4 & -1 & -4 \\ -1 & \lambda - 7 & -1 \\ 0 & 27 - 4\lambda & \lambda \end{vmatrix} \quad (R_1 \rightarrow R_1 + (\lambda - 4)R_2)$$

$$= \begin{vmatrix} 0 & (\lambda - 4)(\lambda - 7) - 1 & -\lambda \\ -1 & \lambda - 7 & -1 \\ 0 & 27 - 4\lambda & \lambda \end{vmatrix}$$

$$= \lambda \cdot [(\lambda - 4)(\lambda - 7) - 1] \lambda + (27 - 4\lambda) \lambda$$

$$= \lambda [\lambda^2 - 11\lambda + 27 + 27 - 4\lambda]$$

$$= \lambda (\lambda^2 - 15\lambda + 54)$$

$$\left(\lambda = \frac{1}{2} [15 \pm \sqrt{225 - 216}] \right) = \left\{ \frac{6}{9}, 0 \right\}$$

Eigenvectors

$$\lambda = 0 \quad \lambda I - P \sim P \sim \begin{bmatrix} 1 & 7 & 1 \\ 4 & 1 & 4 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 7 & 1 \\ 0 & -27 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad P\vec{x} = \vec{0}, \quad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$\left. \begin{array}{l} x_1 + x_3 = 0 \\ x_2 = 0 \end{array} \right\} \begin{array}{l} x_2 = -x_1 \\ x_2 = 0 \end{array}$$

Eigenspace spanned by $\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \vec{v}_1$

$$\lambda = 6: \quad 6I - P \sim \begin{bmatrix} 0 & 2(-1) - 1 & -6 \\ -1 & -1 & -1 \\ 0 & 3 & 6 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 2 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 0 & 1 & 2 \\ 1 & 0 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\underline{x_1 = x_3}, \quad x_2 + 2x_3 = 0$$

$$\underline{x_2 = -2x_1}$$

Eigenspace spanned by $\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} = \vec{v}_2$

Since P is symmetric, $P^t = P$, eigenspaces are pairwise orthogonal. Let $\vec{v}_3 = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ be eigenvector for $\lambda = 9$:

$$0 = \vec{v}_1 \cdot \vec{v}_3 = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = x_1 - x_3, \quad \underline{x_3 = x_1}$$

$$\text{and } 0 = \vec{v}_2 \cdot \vec{v}_3 = x_1 - 2x_2 + x_3 = 2(x_1 - x_2)$$

$$\underline{x_1 = x_2} \quad \vec{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

A general sol. for system is

$$\begin{aligned} \vec{x}(t) &= c_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} e^{6t} + c_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^{9t} \\ &= \begin{bmatrix} c_1 + c_2 e^{6t} + c_3 e^{9t} \\ -2c_2 e^{6t} + c_3 e^{9t} \\ -c_1 + c_2 e^{6t} + c_3 e^{9t} \end{bmatrix} \end{aligned}$$

(c_1, c_2, c_3 are arbitrary constants)

Extn: Find $F(t, x, \dot{x})$ with

Euler equation $\ddot{x} - x = 0$

$$\left(\frac{\partial F}{\partial x} - \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}} \right) = 0 \right)$$

$$\text{Try } \frac{\partial F}{\partial \dot{x}} = \dot{x} \text{, so } \frac{d}{dt} \left(\frac{\partial F}{\partial \dot{x}} \right) = \ddot{x}; \quad \frac{\partial F}{\partial x} = -x$$

$$\text{so } F(t, x, \dot{x}) = -\frac{1}{2}x^2 + G(t, \dot{x})$$

$$\text{Hence we try } \underline{F(t, x, \dot{x}) = +\frac{1}{2}x^2 + \frac{1}{2}\dot{x}^2}$$

$$\text{More general: } F(t, x, \dot{x}) = x^2 + \dot{x}^2 + g(x)\dot{x} + f(t)$$

Simpson's Rule ∴ (Proof: Any good book in Calculus)

$$\int_a^{a+h} f(t) dt \quad (f \in C^4[a, a+h])$$

$$= \frac{h}{6} [f'(a) + 4f'(a+\frac{h}{2}) + f'(a+h)] + E_r$$

where $E_r = -\frac{h^5}{2880} f^{(4)}(c)$, some $c \in (a, a+h)$

Let's try it on $\int_0^\pi \frac{\sin t}{t} dt$

$$\max_x S_i(x) = S_i(\pi) = \int_0^\pi \frac{\sin t}{t} dt$$

$$S_i'(0) = 1, \quad S_i'(\pi) = \frac{\sin \pi}{\pi} = 0$$

$$S_i'(\frac{\pi}{2}) = \frac{\sin \frac{\pi}{2}}{\pi/2} = \frac{2}{\pi}$$

So

$$S_i(\pi) \approx \frac{\pi}{6} [1 + 4 \cdot \frac{2}{\pi} + 0]$$

$$= \frac{\pi}{6} (1 + \frac{8}{\pi}) = 1.8569\dots$$

KNOWN : $S_i(\pi) = 1.85193705\dots$

So $E_r = 1.8519 - 1.8569 = -0.005\dots = -5 \cdot 10^{-3}$

Problem (a) Do this for 2 subintervals:

$$[0, \frac{\pi}{2}] \text{ and } [\frac{\pi}{2}, \pi]$$

(b) for 4 subintervals: $[0, \frac{\pi}{4}], \dots, [\frac{3\pi}{4}, \pi]$

(c) Read about Euler's method
and the improved Euler method:
EP p. 430 ch. 6.1