

## Exam MAT2440, spring 2017 — solutions

### Problem 1

Let  $A$  be the matrix

$$A = \begin{pmatrix} -1 & 0 & 1 \\ 0 & -3 & 4 \\ 0 & -1 & 1 \end{pmatrix}.$$

Determine  $\exp(tA)$ .

Let  $b(t)$  be given as

$$b(t) = \begin{pmatrix} e^{-t} \\ 0 \\ 0 \end{pmatrix}.$$

Find the solution of the differential equation

$$\dot{x} = Ax + b$$

with  $x(0) = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ .

a) One finds that the characteristic polynomial of  $A$  equals  $(\lambda + 1)^2$  so that  $-1$  is an eigenvalue of multiplicity 3. Let  $N = A + I$ , then  $N$  is nilpotent and of course it commutes with  $I$ , and one has

$$N = \begin{pmatrix} 0 & 0 & 1 \\ 0 & -2 & 4 \\ 0 & -1 & 2 \end{pmatrix}$$

One finds

$$N^2 = \begin{pmatrix} 0 & -1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

and  $N^3 = 0$ . It follows that  $\exp(tA) = \exp t(-I + N) = \exp(-tI) \exp(tN)$  and hence

$$\exp tA = e^{-t} \exp tN = e^{-t}(I + tN + t/2 \cdot N^2) = e^{-t} \begin{pmatrix} 1 & -1/2 \cdot t^2 & t^2 + t \\ 0 & 1 - 2t & 4t \\ 0 & -t & 1 + 2t \end{pmatrix}$$

b) Using  $\exp -tA$  as an integrating factor brings the equation on the form

$$d/dt(e^{-tA}x(t)) = e^{-At}b(t).$$

Computing  $e^{-tA}b(t)$  gives

$$e^{-At}b(t) = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}.$$

Integrating and taking care of the initial value gives

$$e^{-tA}x(t) = \begin{pmatrix} t+1 \\ 2 \\ 1 \end{pmatrix}.$$

Finally, one finds

$$x(t) = e^{tA} \begin{pmatrix} t+1 \\ 2 \\ 1 \end{pmatrix} = e^{-t} \begin{pmatrix} 2t+1 \\ 2 \\ 1 \end{pmatrix}.$$

## Problem 2

Consider the optimization problem

$$J(x) = \int_0^1 (2x^2 + 2x\dot{x} + \dot{x}^2) dt \quad x(0) = 0 \quad x(1) = 1.$$

Determine the corresponding Euler-Lagrange equation and find the general solution of it.

Determine a function  $x(t)$  with  $x(0) = 0$  and  $x(1) = 1$  such that  $J(x)$  is minimal.

a) The integrand in  $J(x)$  is derived from the function  $L(q, p) = 2q^2 + 2qp + p^2$ . One finds  $L_q = 4q + 2p$  and  $L_p = 2q + 2p$ . Hence the EL-equation becomes

$$L_q(x, \dot{x}) - d/dt(L_p(x, \dot{x})) = 4x + 2\dot{x} - d/dt(2x + 2\dot{x}) = 4x - 2\ddot{x} = 0$$

or

$$\ddot{x} = 2x.$$

The general solution of the EL-equation is  $x(t) = Ae^{\sqrt{2}t} + Be^{-\sqrt{2}t}$ .

b) The condition  $x(0) = 0$  gives  $B = -A$  and  $x(1) = 1$  gives  $Ae^{\sqrt{2}} + Be^{\sqrt{2}} = 1$ , that is  $A(e^{\sqrt{2}} - e^{-\sqrt{2}}) = 1$ ; that is  $A = (e^{\sqrt{2}} - e^{-\sqrt{2}})^{-1}$ . It follows that

$$x(t) = \frac{e^{\sqrt{2}t} - e^{-\sqrt{2}t}}{e^{\sqrt{2}} - e^{-\sqrt{2}}}.$$

This is a minimum since  $L$  is convex; indeed,  $L_{qq} = 4$ ,  $L_{pq} = 2$  and  $L_{pp} = 2$  which gives the Hessian

$$\det \begin{pmatrix} 4 & 2 \\ 2 & 2 \end{pmatrix} = 4$$

which is positive, and as  $L_{pp}$  and  $L_{qq}$  are positive as well,  $L$  is convex.

### Problem 3

Let  $\alpha > 0$ . Show that  $f(x) = x^{1/2}$  is Lipschitz in the interval  $[\alpha, \infty)$  and give a Lipschitz constant. Is  $f(x)$  Lipschitz in any interval of type  $[0, \beta]$ ?

Consider the differential equation

$$\dot{x} = 2x^{1/2} \quad (*)$$

in the region  $E = \{x \in \mathbb{R} \mid x > 0\}$ . Determine the general solution of the equation and for each  $t_0 \in \mathbb{R}$  and each  $x_0 \in E$  a solution with  $x(t_0) = x_0$ . Give an argument for why it is unique.

Let now  $F = \{x \in \mathbb{R} \mid x \geq 0\}$ . Show that for every  $t_0$  there are at least two solutions of  $(*)$  in  $F$  with  $x(t_0) = 0$  and that both are determined for all  $t$ .

a) One has  $f'(x) = 1/2 \cdot x^{-1/2}$  which is decreasing for  $x > 0$ . Our function  $f$  is  $C^1$  on intervals  $\langle x, y \rangle \subseteq \langle \alpha, \infty \rangle$  with  $0 < \alpha$ . The Mean Value Theorem gives

$$|f(x) - f(y)| = 1/2 \cdot c^{-1/2} |x - y| \leq 1/2 \cdot \alpha^{-1/2} |x - y|$$

and  $f$  is Lipschitz in  $\langle \alpha, \infty \rangle$  with a Lipschitz constant  $1/2 \cdot \alpha^{-1/2}$ . The function  $f$  is not Lipschitz in  $[0, \beta]$ , since again by the Mean Value Theorem one has

$$f(x) = 1/2 \cdot c^{-1/2} x$$

where  $0 < c < x$  and  $1/2 \cdot c^{-1/2} \rightarrow \infty$  when  $x \rightarrow 0$ .

b) Separation of variables gives when  $x > 0$  that

$$\frac{dx}{2\sqrt{x}} = dt$$

integrating we find

$$\sqrt{x} = t + c$$

hence

$$x = (t + c)^2.$$

It is a solution for  $t > -c$ , for  $\dot{x} = 2(t+c)$  must be positive (equal to  $2x^{-1/2}$  which is positive by definition). Given  $t_0$  and  $x_0$  the unique solution with  $x(t_0) = x_0$  is

$$x(t) = (t + x_0^2 - t_0)^2$$

c) The constant function  $x(t) = 0$  is obviously a solution of (\*) in the region  $F$ , and satisfies  $x(t_0) = 0$ . Another solution with  $x(t_0) = 0$  is the one given as

$$x(t) = \begin{cases} 0 & \text{for } t \leq t_0 \\ (t - t_0)^2 & \text{for } t \geq t_0 \end{cases}$$

Since  $\lim_{t \rightarrow t_0^+} (t - t_0)^2 = \lim_{t \rightarrow t_0^+} 2(t - t_0) = 0$  this is continuously differentiable and it satisfies (\*).

### Problem 4

Consider the non-linear system

$$\begin{aligned} \dot{x} &= y - yx & (**) \\ \dot{y} &= x + yx. \end{aligned}$$

Show that the equilibria of the system (\*\*) are  $(0, 0)$  and  $(1, -1)$ , and determine the linearization of the system in each of these. Determine the type of linearizations.

Let  $z(t) = (x(t), y(t))$  be a solution of the system (\*\*). Show that  $x(t) + y(t) = Ae^t$  for a suitable constant  $A$ . Show that if  $z(0)$  lies on the line  $L$  given by  $y + x = 0$ , then  $z(t)$  lies there for all  $t$ .

Let  $(a, b)$  be a point *not* lying on the line  $L$ , and let  $z(t)$  be the solution with  $z(0) = (a, b)$ . Show that  $z(t)$  is not bounded when  $t \rightarrow \infty$ .

a) The equilibria are the solutions of the equations

$$\begin{aligned} y - yx &= 0 \\ x + yx &= 0, \end{aligned}$$

or

$$\begin{aligned} y(1 - x) &= 0 \\ x(1 + y) &= 0. \end{aligned}$$

Hence the equilibria are  $(0, 0)$  and  $(1, -1)$

The Jacobian matrix is

$$J(x, y) = \begin{pmatrix} -y & 1 - x \\ 1 + y & x \end{pmatrix}$$

In  $(0, 0)$  one has

$$J(0, 0) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

with eigenvalues  $\pm 1$ . Hence the linearization is a saddle. In  $(1, -1)$  one finds

$$J(1, -1) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

which is an unstable node.

b) Adding the two equations in (\*\*) gives  $\dot{x} + \dot{y} = x + y$ ; That is  $x(t) + y(t) = Ae^t$ , for a constant  $A$ . If  $x(0) + y(0) = 0$ , it follows that  $A = 0$ , hence  $x(t) + y(t) = 0$  for all  $t$ , and  $z(t)$  lies on  $L$  for all  $t$ .

c) If  $z(t)$  were bounded, one could find a constant  $M$  such that  $|x(t)| < M$  and  $|y(t)| < M$  for all  $t$ , but as  $z(0)$  does not lie on  $L$ , one has  $x(t) + y(t) = Ae^t$  with  $A \neq 0$ . Hence the inequality

$$|A|e^t = |x(t) + y(t)| \leq |x(t)| + |y(t)| \leq 2M$$

would be true for all  $t$ , which is impossible since  $|A|e^t \rightarrow \infty$  when  $t \rightarrow \infty$ .

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