

MAT 2500 20.10.2020

6.6.6. Gi $\alpha: l \rightarrow l'$ med sentrum C
 skal visse at det finnes $T: \mathbb{P}^2 \rightarrow \mathbb{P}^2$
 med C som fokuspunkt og $T|_l = \alpha$
 $R \in l$ så $T(R) = \alpha(R)$.

Kan anta $C = (0:0:1)$
 $l: x_2 = 0$
 $l': Ax_0 + Bx_1 + Cx_2 = 0$

$$T = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

- C fokuspunkt
 $T(C) = \lambda \cdot C$

$$\begin{pmatrix} c \\ f \\ i \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ \lambda \end{pmatrix} \quad \underline{c=f=0 \quad i=\lambda}$$

- $P_1 = (1:0:0) \in l$:
 Linje $P_1C: x_1 = 0$
 $T(P_1) = \alpha(P_1) = P_1C \cap l'$

$$\left. \begin{array}{l} Ax_0 + Bx_1 + Cx_2 = 0 \\ x_1 = 0 \end{array} \right\} \quad \left. \begin{array}{l} Ax_0 + Cx_2 = 0 \\ x_1 = 0 \end{array} \right\}$$

$$\begin{pmatrix} a \\ d \\ g \end{pmatrix} = T(P_1) = \alpha(P_1) = \mu \begin{pmatrix} -c \\ 0 \\ A \end{pmatrix}$$

$$\begin{cases} a = -\mu c \\ d = 0 \\ g = \mu A \end{cases}$$

- $P_2 = (0:1:0) \in l$:
 Linje $P_2C: x_0 = 0$
 $T(P_2) = \alpha(P_2) = P_2C \cap l'$

$$\left. \begin{array}{l} Ax_0 + Bx_1 + Cx_2 = 0 \\ x_0 = 0 \end{array} \right\} \quad \left. \begin{array}{l} Bx_1 + Cx_2 = 0 \\ x_0 = 0 \end{array} \right\}$$

$$\begin{pmatrix} b \\ c \\ h \end{pmatrix} = T(P_2) = \alpha(P_2) = \nu \begin{pmatrix} 0 \\ -c \\ B \end{pmatrix}$$

$$\begin{cases} b = 0 \\ e = -\nu c \\ h = \nu B \end{cases}$$

$$T = \begin{pmatrix} -\mu c & 0 & 0 \\ 0 & -\nu c & 0 \\ \mu A & \nu B & \lambda \end{pmatrix}$$

- Generelt punkt $P = (y_0: y_1: 0) \in l$

$$T(P) = \begin{pmatrix} -\mu c y_0 \\ -\nu c y_1 \\ \mu A y_0 + \nu B y_1 \end{pmatrix} \quad \text{ni liggende på } l'$$

$$PC: \begin{pmatrix} x_0 & x_1 & x_2 \\ y_0 & y_1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = G$$

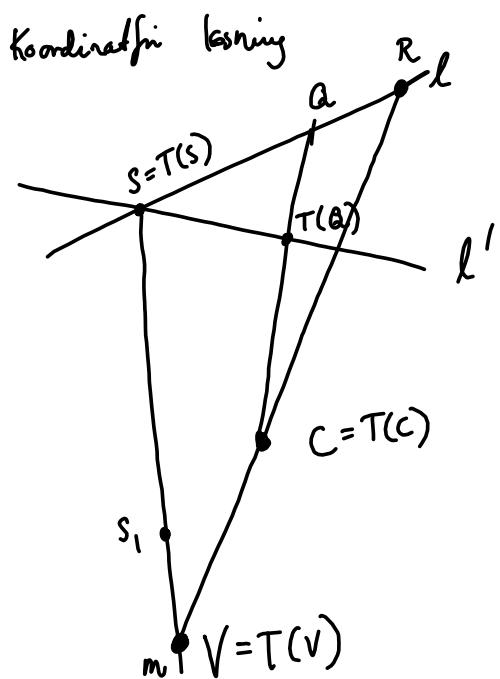
$$\underline{y_1 x_0 - y_0 x_1 = 0}$$

$$T(P) \in PC \text{ gir } y_1(-\mu c y_0) - y_0(-\nu c y_1) = 0$$

$$c y_0 y_1 (-\mu + \nu) = 0 \quad \text{si } \underline{\nu = \mu}$$

$$T = \begin{pmatrix} -\mu c & 0 & 0 \\ 0 & -\mu c & 0 \\ \mu A & \mu B & \lambda \end{pmatrix} \quad \text{gir ordnet transformasjon}$$

- Kan velge $\underline{\mu = \lambda = 1}$



$$\begin{aligned}
 Q &\mapsto T(Q) \\
 C &\mapsto C = T(C) \\
 S &\mapsto S = T(S) \\
 S_1 &\mapsto S_1 = T(S_1) \\
 \text{Fixerer } m \text{ punktvis} \\
 V &= T(V) \\
 C &= T(C) \\
 VC &= RC = T(V)T(C) \\
 T(R) &= \alpha(R)
 \end{aligned}$$

$$6.6.7. \quad T: \mathbb{P}^2 \rightarrow \mathbb{P}^2 \quad \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & -1 \\ 0 & 2 & 4 \end{pmatrix}$$

Fiks punkt til T : $T(P) = \lambda P$ P egenvektor til egenverdi $\lambda \neq 0$.

$$0 = \begin{vmatrix} 2-\lambda & 1 & 0 \\ 0 & 1-\lambda & -1 \\ 0 & 2 & 4-\lambda \end{vmatrix} = (2-\lambda)[(-\lambda)(4-\lambda) - 2(-1)] = (2-\lambda)[4-4\lambda-\lambda+\lambda^2+2] = (2-\lambda)(\lambda^2-5\lambda+6) = (2-\lambda)(\lambda-2)(\lambda-3)$$

$$\begin{array}{ll} \lambda_1 = 2 & \lambda_2 = 3 \\ m_1 = 2 & m_2 = 1 \end{array}$$

$$\lambda_1 = 2: \quad \left(\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & -1 & -1 & 0 \\ 0 & 2 & 2 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$P_1 = (\lambda : 0 : 0) \sim \underline{(1 : 0 : 0)}$$

$$\lambda_2 = 3: \quad \left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & -2 & -1 & 0 \\ 0 & 2 & 1 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$\sim \left(\begin{array}{ccc|c} 2 & 0 & 1 & 0 \\ 0 & \frac{1}{2} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \sim \left(\begin{array}{ccc|c} \frac{1}{2} & 0 & \frac{1}{2} & 0 \\ 0 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$$P_2 = \left(-\frac{1}{2}t : -\frac{1}{2}t : t \right) \sim \underline{(1 : 1 : -2)}$$

P_1 og P_2 er fiks punktene til T .

II Finn alle linjer ℓ med $T(\ell) = \ell$
 $\ell_0: P_1 P_2$ bør være en spesiell linje

$$\ell: ax_0 + bx_1 + cx_2 = 0$$

$$T(\ell): \text{Vilkårlig punkt } P = \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix}$$

$$T(\ell) = \begin{pmatrix} 2 & 1 & 0 \\ 0 & 1 & -1 \\ 0 & 2 & 4 \end{pmatrix} \cdot \begin{pmatrix} y_0 \\ y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 2y_0 + y_1 \\ y_1 - y_2 \\ 2y_1 + 4y_2 \end{pmatrix}.$$

$$P \in \ell \quad k(ax_0 + bx_1 + cx_2) = 0$$

$$T(\ell) \in \ell \quad a(2y_0 + y_1) + b(y_1 - y_2) + c(2y_1 + 4y_2) = 0$$

$$\text{I} \quad y_0: \quad k \cdot a = 2 \cdot a$$

$$\text{II} \quad y_1: \quad k \cdot b = a + b + 2c$$

$$\text{III} \quad y_2: \quad k \cdot c = -b + 4c$$

$$\text{A I: } a = 0$$

$$\text{II: } kb = b + 2c$$

$$\cancel{(k-1)b - 2c = 0}$$

$$\text{III: } kc = -b + 4c$$

$$\cancel{b + (k-4)c = 0}$$

$$\text{B } k=2$$

$$\text{II: } 2b = a + b + 2c$$

$$0 = a - b + 2c$$

$$\text{III: } 2c = -b + 4c$$

$$0 = -b + 2c$$

$$\left. \begin{array}{l} a=0 \\ b=2c \end{array} \right\}$$

$$\bullet \quad \left(\begin{array}{cc|c} k-1 & -2 & 0 \\ 1 & k-4 & 0 \end{array} \right)$$

$$0 = (k-1)(k-4) - 1(-2)$$

$$= k^2 - 5k + 6$$

$$= \underline{(k-2)(k-3)}$$

$$k=2: \left(\begin{array}{cc|c} 1 & -2 & 0 \\ 1 & -2 & 0 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right) \quad \begin{array}{l} a=0 \\ b=2c \end{array}$$

$$\ell: 2(0 \cdot x_0 + 2c \cdot x_1 + c \cdot x_2) = 0$$

$$2c(2x_1 + x_2) = 0$$

$$\underline{\underline{2x_1 + x_2 = 0}}$$

$$\begin{array}{l} P_1 = (1:0:c) \\ P_2 = (1:1:-2) \end{array}$$

$$k=3: \left(\begin{array}{cc|c} 2 & -2 & 0 \\ 1 & -1 & 0 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right) \quad b=c, c \in \mathbb{R}$$

$$\ell: 3(cx_1 + cx_2) = 0$$

$$3c(x_1 + x_2) = 0$$

$$\underline{x_1 + x_2 = 0} \quad \text{en linje gjennom } P_1$$

Hør med generaliserte egenvektorar å gjøre.

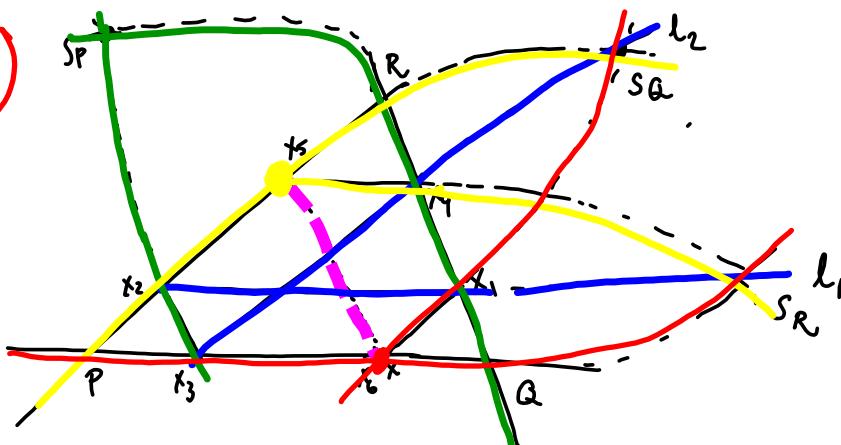
6.6.8 $T: \mathbb{P}^2 \rightarrow \mathbb{P}^2$ har alltid minst ett filospunkt.

- Nok å vise minst én ikke-null egenverdi
- Anta at alle egenverdier = 0

$$0 = \det(T - 0 \cdot I) = \det T$$

Umulig, for T er INVERTABLE matrise.
først T er en projektiv transformasjon

15.①



$$l_1 : x_1 \ x_2 \ S_R$$

$$l_2 : x_3 \ x_4 \ S_Q$$

$$x_1 x_4 \cap x_2 x_3$$

 S_P

$$x_2 S_Q \cap x_4 S_R$$

 X_5

$$x_3 S_R \cap x_1 S_Q$$

 \times

✓ Pappus' teorem er S_P, X_5 og X kollinære

$$X \in X_5 S_P \text{ og } X \in PQ$$

✓ konstruksjonen er x_6, S_P og X_5 kollinære

$$x_6 \in X_5 S_P \text{ og } x_6 \in PQ$$

$$\text{Så } X = X_6$$

(5-2)

En mulig formulering:

La l_1 og l_2 være to linjer i \mathbb{R}^2 .

La A_i, B_i, C_i være tre punkter på l_i .

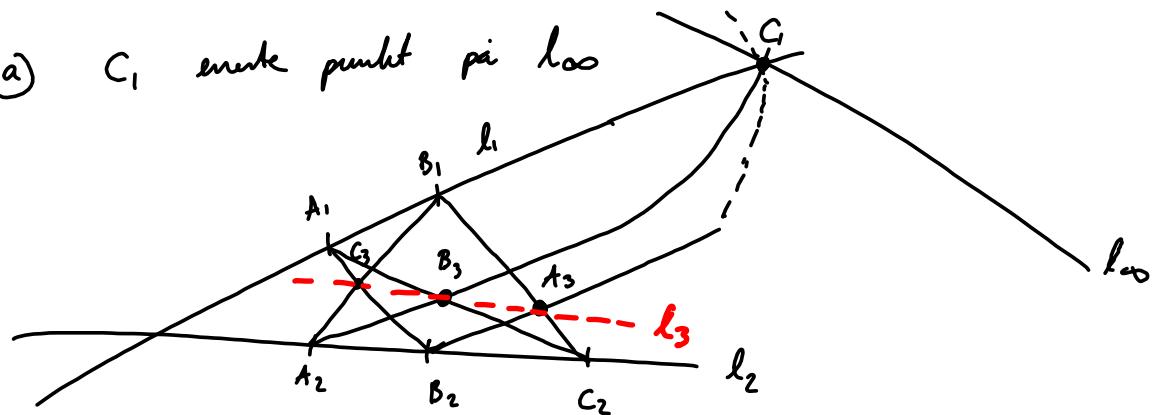
Hvis A_1B_2 snittet A_2B_1 i C_3

og B_1C_2 snittet B_2C_1 i A_3

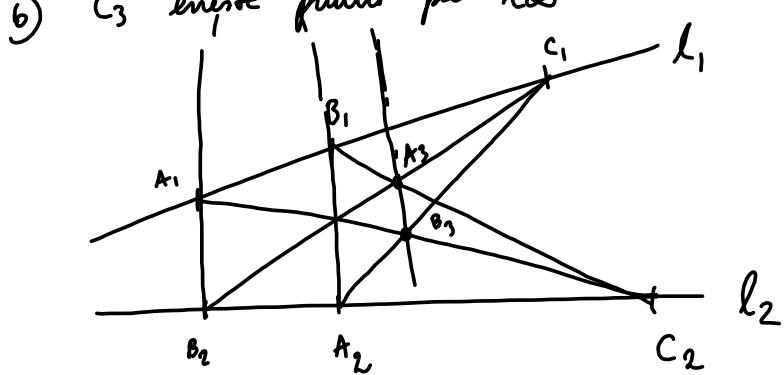
og C_1A_2 snittet C_2A_1 i B_3 ,

da er A_3, B_3, C_3 kollineare.

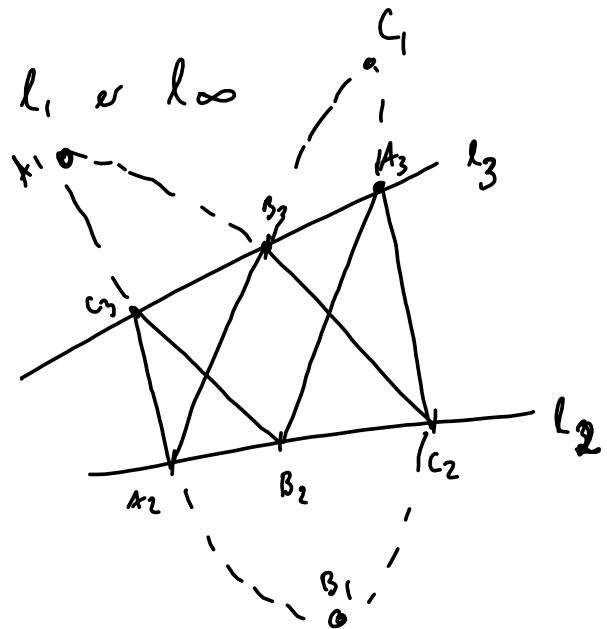
a) C_1 er øyete punktet på los



b) C_3 er øyete punktet på los



c) l_1 er los



d) $\Delta A_1 B_2 \sim C_3$
 $A_1 B_2 \cap A_2 B_1$

