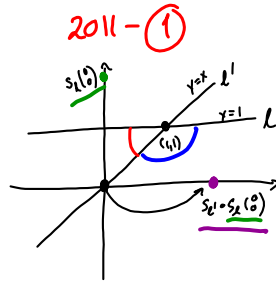


kollinear \Leftrightarrow
 P, Q, R

$$\frac{\overline{BP}}{\overline{PC}} \cdot \frac{\overline{CQ}}{\overline{QA}} \cdot \frac{\overline{AR}}{\overline{RB}} = -1$$



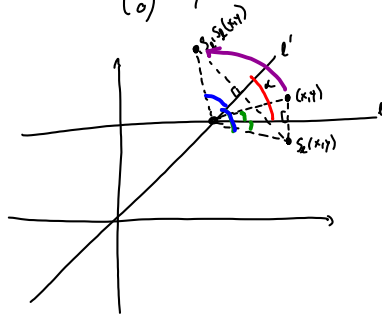
s_x, s_x' speilinger

$\Rightarrow g = s_x' \circ s_x$

Oppg. 2.4.11

- s_x' og s_x er orienteringsbevarende, g er orienteringsbevarende.
- g er enten translasjon eller rotasjon
- l' er filloper for s_x'
 l er --- for s_x
 $l \cap l'$ er filloper for $s_x' \circ s_x$
- Siden g er rotasjon
- filloper er $(1,1)$
- Rotasjonsvinkel er $\frac{\pi}{2}$
siden $g \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$

$$g \begin{pmatrix} 0 \\ 0 \end{pmatrix} = s_x' \circ s_x \begin{pmatrix} 0 \\ 0 \end{pmatrix} = s_x' \begin{pmatrix} 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$



$$2\beta - 2\gamma = \delta$$

$$\beta - \gamma = \alpha$$

Oppg 2-2b) $s_x = t_{\vec{a}} \circ s_x' \circ t_{-\vec{a}}$ $l \parallel l'$
 \vec{a} ortogonal til l'
 l' gjennom origo l gjennom \vec{a}

$$s_x = t_{\begin{pmatrix} 1 \\ 0 \end{pmatrix}} \circ s_{y=0} \circ t_{\begin{pmatrix} -1 \\ 0 \end{pmatrix}} \quad s_{y=0} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$s_x' = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad l': y=x$$

$$g \begin{pmatrix} x \\ y \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}_{s_x'} \cdot \underbrace{\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}}_{s_x} \cdot t_{\begin{pmatrix} 0 \\ -1 \end{pmatrix}} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \cdot t_{\begin{pmatrix} 0 \\ -1 \end{pmatrix}} \begin{pmatrix} x \\ y-1 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ 1-y \end{pmatrix}$$

F.P. $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 2-y \\ x \end{pmatrix}$

$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ 2-y \end{pmatrix}$$

$$\begin{cases} x+y=2 \\ x-y=0 \end{cases} \Rightarrow x=y=1$$

$$= \begin{pmatrix} 2-y \\ x \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix} + \begin{pmatrix} -y \\ x \end{pmatrix}$$

$$= t_{\begin{pmatrix} 0 \\ 0 \end{pmatrix}} \cdot \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} \cos \frac{\pi}{2} & -\sin \frac{\pi}{2} \\ \sin \frac{\pi}{2} & \cos \frac{\pi}{2} \end{pmatrix} \quad \begin{cases} a = \cos \theta \\ l = \sin \theta \end{cases} \Rightarrow \theta = \frac{\pi}{2}$$

b) $t = t_{\begin{pmatrix} 0 \\ 2 \end{pmatrix}}$

$$t_g^{\circ} = t_{\begin{pmatrix} -2 \\ 0 \end{pmatrix}} \circ t_{\begin{pmatrix} 0 \\ 2 \end{pmatrix}} \circ g_{0, \frac{\pi}{2}} = g_{0, \frac{\pi}{2}}$$

$$t_g \begin{pmatrix} 0 \\ 0 \end{pmatrix} = t_{\begin{pmatrix} -2 \\ 0 \end{pmatrix}} \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} -2+2 \\ 0+0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, s_{\frac{\pi}{2}} \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

og samme vinkel