

Summary

- Axiomatization of root system
- Dynkin diagrams.

Def. A root system is given by

- Euclidean space E
- fin. subset $R \subset E$ s.t.

1) R spans E

2) $\alpha \in R, k \in \mathbb{Z} : k\alpha \in R \Leftrightarrow k = \pm 1$

3) $s_\alpha(v) = v - \frac{2(\alpha, v)}{(\alpha, \alpha)} \alpha \quad (\alpha \in R)$

maps R to R

4) $n_{\alpha, \beta} = \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \mathbb{Z}$

Prop $\alpha, \beta \in R \rightarrow$ angles between α & β is

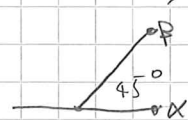
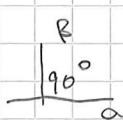
$\frac{\pi}{2}, \frac{\pi}{3}, \frac{\pi}{4}, \frac{\pi}{6}, \pi - (\text{one of these})$

Proof $n_{\alpha, \beta} n_{\beta, \alpha} = 4 \frac{(\alpha, \beta)^2}{(\alpha, \alpha)(\beta, \beta)} = 4 \cos^2 \theta$

for the angle θ .

$\Rightarrow \cos \theta = \pm \frac{\sqrt{a}}{2}$ for $a \in \mathbb{N}$ only possible

for $a = 0, 1, 2, 3$.

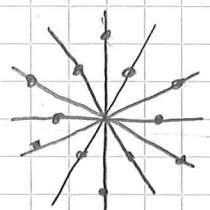
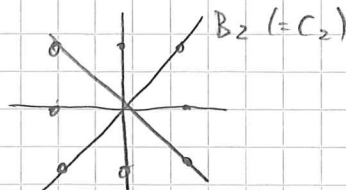
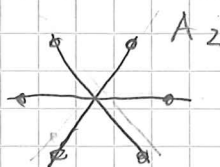
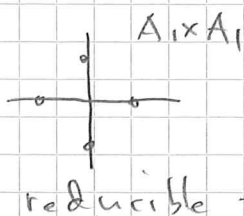


$\|\alpha\| = \|\beta\|$

$\|\beta\| = \sqrt{2} \|\alpha\|$

$\|\beta\| = \sqrt{3} \|\alpha\|$

Ex. If $\dim E = 2$ R is one of:



Rem $(E_1, R_1), (E_2, R_2)$ root sys $\Rightarrow (E \times E_2, R_1 \times R_2)$

Def irred. root sys: \mathbb{A} decomp. as above.

So far: \mathfrak{g} simple Lie alg., \mathbb{R} COJ Cartan

\rightsquigarrow root system by

- R : roots (nonzero eigenval funcs. of $\text{ad}_{\mathfrak{h}}$)

$$\text{so } \mathfrak{g} = \mathfrak{h} \oplus \left(\bigoplus_{\alpha \in R} \mathfrak{g}_{\alpha} \right)$$

- $E = R \wedge_{\mathbb{W}} = R \wedge_{\mathbb{R}}$ real span of $R \subset \mathfrak{h}^*$

inner prod. \leftrightarrow Killing form on.

$$E^* = \mathfrak{h}_0 = \langle H_{\alpha} = [E_{\alpha}, F_{\alpha}] : \alpha \in R \rangle_{\mathbb{R}}$$

Goal:

1. classify irred. root systems by

Dynkin Diagrams $(E, R) \rightsquigarrow$ diag.

2. check that irred. root sys. come from simple Lie algs

diag $\rightsquigarrow (\mathfrak{g}, R)$ (\rightsquigarrow "root sys", will be inverse op.)

Dynkin Diagrams

