

Introduction.

Paradigm of algebraic topology :

allow continuous deformation of spaces, maps, ...
and see which properties remain the same



do not care about : distance, homeomorphism type, ...
care about : "number of holes / loops up to deform.", ...

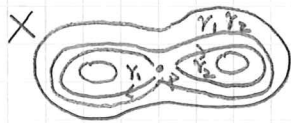
tools : abstract algebra ; groups, rings, modules, ...

capture "loops up to cont. def.", "composition of structures in such loops" etc.

Main goals of this course :

1. fundamental group $\pi_1(X, p)$
↑ space ↙ basepoint

"loops in X based at p , up to cont def"
group law with path composition



2. (singular) homology groups $H_n(X)$ $n=0, 1, 2, \dots$

"formal linear comb. of maps $S^n \xrightarrow{\sigma} X$; $a\sigma_1 + b\sigma_2, \dots$
up to cont. def.

3. give computable models of $\pi_1(X), H_n(X)$ for spaces given by glueing basic parts.



Chapter 0 : Homotopy

Want : represent continuous deformation of maps
(and spaces).

Example. $X = Y = \{ (x, y) \in \mathbb{R}^2 : x^2 + y^2 \leq 1 \}$
 $f_t : X \rightarrow Y, \quad f_t(x, y) = (tx, ty) \quad 0 \leq t \leq 1$
 $f_1 = \text{id}, \quad f_0(x, y) = (0, 0)$



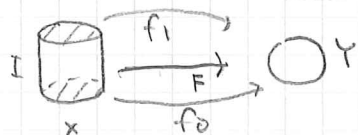
Convention X, Y : topological spaces, $f : X \rightarrow Y$ cont. map
 $I = [0, 1]$ unit interval

Def. $f_0, f_1 : X \rightarrow Y$; f_0 and f_1 are homotopic

if $\exists F : X \times I \rightarrow Y$ s.t. $f_0(x) = F(x, 0), f_1(x) = F(x, 1)$

write $f_0 \simeq f_1$ or $f_0 \simeq_h f_1$

say F is a homotopy between f_0 and f_1 .



Morally : F represents a cont. family $f_t : X \rightarrow Y$.

(to be precise : cont map $I \rightarrow \mathcal{C}(X, Y)$
 \uparrow space of cont maps with compact-open topology

"Shrink down a space"

Def $A \subset X$ is a deformation retract if

$\exists r : X \rightarrow A$ s.t. $\begin{cases} r(a) = a \text{ for } a \in A \\ \text{id}_X \text{ and } r \text{ are homotopic as} \\ \text{cont. maps } X \rightarrow X \end{cases}$

Example $X = \{ (x, y) \in \mathbb{R}^2 : 1 \leq \sqrt{x^2 + y^2} \leq 3 \}$
 $A = \{ (x, y) : \sqrt{x^2 + y^2} = 2 \}$



$r(x, y) = \text{"projection" from } X \text{ to } A$

$F(x, y, t) = (1-t)r(x, y) + t(x, y)$

"Spaces up to cont. deform"

Def. X and Y are homotopy equivalent if

$$\exists f: X \rightarrow Y, g: Y \rightarrow X \text{ s.t.}$$

1. fg and id_Y are homotopic (as maps $Y \rightarrow Y$)

2. gf and id_X are homotopic. (as $X \rightarrow X$)

write $X \simeq Y, X \sim_h Y$, etc.

Example $A \subset X$ def. retract $\Rightarrow A \simeq X$

$i: A \rightarrow X$ inclusion map, $r: X \rightarrow A$ retract map.

$$\Rightarrow \begin{cases} ri = \text{id}_A & (r(a) = a) \\ ir \sim_h \text{id}_X & (ir = r \text{ as } X \rightarrow X \sim_h \text{id}_X) \end{cases}$$

Def. pt: top. sp. with a single element

X is contractible if $X \simeq \text{pt}$

Example $D^k = \{(x_1, \dots, x_k) \in \mathbb{R}^k : x_1^2 + \dots + x_k^2 \leq 1\}$
closed unit ball of \mathbb{R}^k

$\Rightarrow A = \{(0, \dots, 0)\}$ is a def. retr.