

Brownian Motion and Stochastic Calculus

Recall first some definitions given in class.

Definition 1 (Def. Class) *A standard Brownian motion is a process satisfying*

1. *W has continuous paths P -a.s.,*
2. *$W_0 = 0$, P -a.s.,*
3. *W has independent increments,*
4. *For all $0 \leq s < t$, the law of $W_t - W_s$ is a $\mathcal{N}(0, (t - s))$.*

Definition 2 *X is a Gaussian process if for any $t_1, t_2, \dots, t_n, \in \mathbb{R}_+, n \in \mathbb{N}$ the vector*

$$(X_{t_1}, X_{t_2}, \dots, X_{t_n}),$$

is multivariate normal.

A useful criterion to check if a vector is multivariate normal is the following

Proposition 3 *A vector (X_1, \dots, X_n) is multivariate normal if and only if for all $\lambda_i \in \mathbb{R}, i = 1, \dots, n$ one has that the random variable $\sum_{i=1}^n \lambda_i X_i$ is (univariate) normal.*

Remark 4 *Note that, by proposition 3, we may assume that the times $\{t_i\}_{i=1, \dots, n}$ in definition 2 are ordered, i.e., $0 \leq t_1 < t_2 < \dots < t_n$.*

In Exercise 1 the following alternative definition of Brownian motion is introduced.

Definition 5 (Def. Gaussian) *A standard Brownian motion is a process satisfying*

- a) *W has continuous paths P -a.s.,*
- b) *W is a Gaussian process,*
- c) *W is centered ($\mathbb{E}[W_t] = 0$) and the covariance function*

$$K(s, t) \triangleq \mathbb{E}[(W_t - \mathbb{E}[W_t])(W_s - \mathbb{E}[W_s])] = \mathbb{E}[W_t W_s] = \min(s, t).$$

Recall also the definition of \mathbb{F} -Brownian motion.

Definition 6 *A \mathbb{F} -Brownian motion W is a real stochastic process adapted to \mathbb{F} satisfying*

1. *W has continuous paths P -a.s.,*
2. *$W_0 = 0$, P -a.s.,*
3. *For all $0 \leq s < t$, the random variable $W_t - W_s$ is independent of \mathcal{F}_s .*
4. *For all $0 \leq s < t$, the law of $W_t - W_s$ is a $\mathcal{N}(0, (t - s))$.*

1. In this exercise we have to show that Def. Class is equivalent to Def. Gaussian

Def. Class \implies Def. Gaussian.: Clearly 1. \Rightarrow a). Properties 3. and 4. yields that for any $0 \leq t_1 < t_2 < \dots < t_n, n \in \mathbb{N}$ the vector

$$(W_{t_n} - W_{t_{n-1}}, W_{t_{n-1}} - W_{t_{n-2}}, \dots, W_{t_1})$$

has multivariate normal distribution and, by a linear transform, we get that

$$(W_{t_1}, \dots, W_{t_{n-1}}, W_{t_n})$$

has a multivariate normal distribution. Alternatively, for all $\lambda_i \in \mathbb{R}, i = 1, \dots, n$ we have that

$$\sum_{i=1}^n \lambda_i W_{t_i} = \sum_{i=1}^n \lambda_i \sum_{j=1}^i (W_{t_j} - W_{t_{j-1}}) = \sum_{j=1}^n \left(\sum_{i=j}^n \lambda_i \right) (W_{t_j} - W_{t_{j-1}}),$$

which is a univariate normal by properties 3. and 4. Hence, we can conclude that W is a Gaussian process. By 4. we get that $\mathbb{E}[W_t] = 0$ for all $t \geq 0$. Moreover, if $s < t$ we have that

$$\begin{aligned} K(s, t) &= \mathbb{E}[W_s W_t] = \mathbb{E}[W_s(W_t - W_s) + W_s^2] = \mathbb{E}[W_s(W_t - W_s)] + \mathbb{E}[W_s^2] \\ &= \mathbb{E}[W_s] \mathbb{E}[(W_t - W_s)] + s = s, \end{aligned}$$

where we have used 3. and 4. A similar reasoning can be done if $t < s$, so we get that $K(s, t) = \min(s, t)$.

Def. Gaussian \implies Def. Class.: Clearly a) \Rightarrow 1. By property c) we have that $\mathbb{E}[W_0] = 0$ and $\mathbb{E}[W_0^2] = K(0, 0) = 0$, which yields that $W_0 = 0, P$ -a.s. and, hence, property 2. is satisfied. Note that if (Z_1, Z_2) is bivariate Gaussian then Z_1 is independent of Z_2 if and only if $\mathbb{E}[Z_1 Z_2] = \mathbb{E}[Z_1] \mathbb{E}[Z_2]$. In order to prove 3., we have to show that $W_t - W_s$ is independent of $W_v - W_u$ for any $0 \leq u \leq v \leq s \leq t$. As W is a Gaussian process by b), we have that $(W_t - W_s, W_v - W_u)$ is bivariate Gaussian and it suffices to prove that

$$\mathbb{E}[(W_t - W_s)(W_v - W_u)] = 0,$$

but using property c) we get that

$$\begin{aligned} \mathbb{E}[(W_t - W_s)(W_v - W_u)] &= K(t, v) - K(t, u) - K(s, v) + K(s, u) \\ &= v - u - v + u = 0. \end{aligned}$$

Finally, by b) again, we have that for all $0 \leq s < t$ the law of $W_t - W_s$ is Gaussian. And using c) we get that

$$\begin{aligned} \mathbb{E}[W_t - W_s] &= \mathbb{E}[W_t] - \mathbb{E}[W_s] = 0, \\ \text{Var}[W_t - W_s] &= \mathbb{E}[(W_t - W_s)^2] \\ &= K(t, t) - K(t, s) - K(s, t) + K(s, s) = t - s, \end{aligned}$$

which yields property 4.

2. W is a Brownian motion, $a > 0$ and \mathbb{F} the minimal augmented filtration generated by W .

(a) $X_t = -W_t, t \in \mathbb{R}_+$: X has continuous paths P -a.s. because W has continuous paths P -a.s.. For any $0 \leq t_1 < t_2 < \dots < t_n, n \in \mathbb{N}$ the vector

$$(X_{t_1}, \dots, X_{t_{n-1}}, X_{t_n}) = (-W_{t_1}, \dots, -W_{t_{n-1}}, -W_{t_n})$$

is Gaussian because $(W_{t_1}, \dots, W_{t_{n-1}}, W_{t_n})$ is Gaussian, as W is a Gaussian process. Moreover

$$\begin{aligned}\mathbb{E}[X_t] &= \mathbb{E}[-W_t] = -\mathbb{E}[W_t] = 0, \\ K(s, t) &= \mathbb{E}[X_s X_t] = \mathbb{E}[(-W_s)(-W_t)] = \mathbb{E}[W_s W_t] = \min(s, t).\end{aligned}$$

Therefore, by the previous exercise we can conclude that X is a Brownian motion. Note also that $\mathbb{F} = \mathbb{F}^X$. This is because $X_t = \varphi(W_t)$, where $\varphi(x) = -x$ is a bijection. This yields that $\sigma(X_t) = \sigma(W_t)$ and, therefore, $\mathcal{F}_t^X = \sigma(X_s : 0 \leq s \leq t) = \sigma(W_s : 0 \leq s \leq t) = \mathcal{F}_t$ for any t . Hence, we can conclude that X is also an \mathbb{F} -Brownian motion.

- (b) $X_t = W_{a+t} - W_a, t \in \mathbb{R} : X$ has continuous paths P -a.s. because W has continuous paths P -a.s.. For any $0 < t_1 < t_2 < \dots < t_n, n \in \mathbb{N}$ the vector

$$(W_a, W_{a+t_1}, \dots, W_{a+t_{n-1}}, W_{a+t_n}),$$

is multivariate normal because W is a Gaussian process. By a linear transformation of the previous vector we get that

$$(W_{a+t_1} - W_a, \dots, W_{a+t_{n-1}} - W_a, W_{a+t_n} - W_a),$$

is also multivariate normal and, hence, the process X is Gaussian. We also have that

$$\begin{aligned}\mathbb{E}[X_t] &= \mathbb{E}[W_{a+t} - W_a] = 0, \\ K(s, t) &= \mathbb{E}[X_s X_t] = \mathbb{E}[(W_{a+s} - W_a)(W_{a+t} - W_a)] \\ &= K(a+s, a+t) - K(a+s, a) - K(a, a+t) + K(a, a) \\ &= \min(a+s, a+t) - \min(a+s, a) - \min(a, a+t) + \min(a, a) \\ &= \min(a+s, a+t) - a = \min(s, t).\end{aligned}$$

Therefore, we can conclude that X is a Brownian motion. However, X is not an \mathbb{F} -Brownian motion because X is not adapted to \mathbb{F} , note that $X_t = W_{a+t} - W_a$ depends on W_{a+t} which is not \mathcal{F}_t measurable.

- (c) $X_t = W_{at^2}, t \in \mathbb{R}_+ : X$ is not a Brownian motion because, although has continuous paths, is Gaussian and centered, one has that

$$K(s, t) = \mathbb{E}[X_s X_t] = \mathbb{E}[X_{as^2} W_{at^2}] = \min(as^2, at^2) \neq \min(s, t).$$

As X is not a Brownian motion, it cannot be an \mathbb{F} -Brownian motion.

3. Let $f \in L^2([0, T])$. First we will show that $X_t = \int_0^t f(s) dW_s \sim \mathcal{N}\left(0, \int_0^t |f(s)|^2 ds\right)$ for every $t \in [0, T]$. Define $f_t(s) \triangleq f(s) \mathbf{1}_{[0, t]}(s)$ and note that $|f_t(s)| \leq |f(s)|$ for all $s \in [0, T]$. As f is deterministic, we have that for all $t \in [0, T]$ the process f_t it is also measurable and adapted and

$$\mathbb{E} \left[\int_0^T |f_t(s)|^2 ds \right] = \int_0^T |f_t(s)|^2 ds \leq \int_0^T |f(s)|^2 ds < \infty.$$

Hence, $f_t \in L^2_{a, T}$ and $X_t = \int_0^t f(s) dW_s = \int_0^T f_t(s) dW_s$. Consider a sequence of partitions

$$\pi^n = \{0 = t_0 < t_1 < t_2 < \dots < t_{n-1} < t_n = T\}, n \geq 1,$$

with $\|\pi^n\| \triangleq \max_{1 \leq i \leq n} |t_i - t_{i-1}|$ converging to zero when n tends to infinity. We can consider the sequence of function $f_{t, n}(s) = \sum_{i=1}^{n-1} f_t(t_i) \mathbf{1}_{[t_i, t_{i+1})}(s)$. We have that $f_{t, n}$ converges λ -a.e. to f_t and

$$\mathbb{E} \left[\int_0^T |f_t(s) - f_{t, n}(s)|^2 ds \right] = \int_0^T |f_t(s) - f_{t, n}(s)|^2 ds \xrightarrow{n \rightarrow \infty} 0,$$

by dominated convergence. Hence, $f_{n, t}(s)$ (as a process in s) is a sequence of simple processes approximating f_t in $L^2_{a, T}$ and, by the construction of the Itô integral, we have that

$$\int_0^T f_{t, n}(s) dW_s \xrightarrow[n \rightarrow \infty]{L^2} \int_0^T f_t(s) dW_s.$$

In addition, for every $n \geq 1$,

$$\int_0^T f_{t,n}(s) dW_s = \sum_{i=1}^{n-1} f_t(t_i) (W_{t_i} - W_{t_{i-1}}),$$

which is a sum of independent Gaussian random variables with law $\mathcal{N}(0, \sum_{i=1}^{n-1} |f_t(t_i)|^2 (t_i - t_{i-1}))$. We recall the following result that we give without proof (it is easy using the relationship between characteristic functions and weak convergence). Let Z_n be a sequence of random variables with laws $\mathcal{N}(0, \sigma_n^2)$. If $Z_n \xrightarrow[n \rightarrow \infty]{L^2} Z_\infty$ then $\sigma_\infty^2 \triangleq \lim_{n \rightarrow \infty} \sigma_n^2 < \infty$ and $Z_\infty \sim \mathcal{N}(0, \sigma_\infty^2)$.

In our case, we have that $Z_\infty = \int_0^T f_t(s) dW_s = \int_0^T f(s) dW_s$ and $\sigma_\infty^2 = \int_0^T f_t^2(s) ds = \int_0^T f^2(s) ds$. Therefore we can conclude that $X_t = \int_0^t f(s) dW_s \sim \mathcal{N}(0, \int_0^t f^2(s) ds)$. Finally, to show that X is a Gaussian process, note that for all $\lambda_i \in \mathbb{R}$, and $\{t_i\}_{i=1, \dots, n} \in \mathbb{R}_+, n \in \mathbb{N}$ we have that

$$\sum_{i=1}^n \lambda_i X_{t_i} = \sum_{i=1}^n \lambda_i \int_0^{t_i} f(s) dW_s = \int_0^T \left(\sum_{i=1}^n \lambda_i f_{t_i}(s) \right) dW_s,$$

which is an univariate Gaussian because $\sum_{i=1}^n \lambda_i f_{t_i}(s) \in L^2([0, T])$. By the properties of the Itô integral, we get that $\mathbb{E}[X_t] = 0$ and $\mathbb{E}[X_s X_t] = \int_0^{\min(s,t)} f^2(u) du$.

4. Let W be a Brownian motion and $\mathbb{F} = \mathbb{F}^W$. Show that the following processes are \mathbb{F} -martingales. A general remark on this kind of problems: If you are given a process that is a regular/smooth transformation of a Brownian motion, the straightforward way of checking that the process is a martingale is to use Itô's formula.

- (a) $X_t = \exp\left(\theta W_t - \frac{\theta^2}{2} t\right), t \in [0, T]$: X is \mathbb{F} -adapted because $X_t = \varphi_t(W_t)$ where φ_t is a Borel measurable function for every $t \in [0, T]$. This means that X_t is $\sigma(W_t)$ -measurable and, in particular, \mathcal{F}_t -measurable because $\sigma(W_t) \subset \mathcal{F}_t$ for every $t \in [0, T]$. $X_t \in L^1(\Omega, \mathcal{F}, P)$, i.e., $\mathbb{E}[|X_t|] < \infty$ because $W_t \sim \mathcal{N}(0, t)$ and, hence,

$$\mathbb{E}[\exp(\theta W_t)] = \exp\left(\frac{\theta^2}{2} t\right),$$

which yields $\mathbb{E}[|X_t|] < \infty$. To check the martingale property $E[X_t | \mathcal{F}_s] = X_s$, we can check that $\mathbb{E}\left[\frac{X_t}{X_s} | \mathcal{F}_s\right] = 1$, because X_s is \mathcal{F}_s -measurable and can go inside the conditional expectation. We have that

$$\begin{aligned} \mathbb{E}\left[\frac{X_t}{X_s} | \mathcal{F}_s\right] &= \mathbb{E}\left[\exp\left(\theta(W_t - W_s) - \frac{\theta^2}{2}(t - s)\right) | \mathcal{F}_s\right] \\ &= \mathbb{E}[\exp(\theta(W_t - W_s)) | \mathcal{F}_s] \exp\left(-\frac{\theta^2}{2}(t - s)\right) \\ &= \mathbb{E}[\exp(\theta(W_t - W_s))] \exp\left(-\frac{\theta^2}{2}(t - s)\right) \\ &= \exp\left(\frac{\theta^2}{2}(t - s)\right) \exp\left(-\frac{\theta^2}{2}(t - s)\right) = 1, \end{aligned}$$

where we have used that $\exp\left(-\frac{\theta^2}{2}(t - s)\right)$ is deterministic, that $\exp(\theta(W_t - W_s))$ is independent of \mathcal{F}_s and the moment generating function of a normal distribution, i.e., for $Z \sim \mathcal{N}(\mu, \sigma^2)$ we have $\mathbb{E}[\exp(\theta Z)] = \exp\left(\mu\theta + \frac{\theta^2}{2}\sigma^2\right)$.

- (b) $Y_t = e^{t/2} \cos(W_t), t \in [0, T]$: Y is \mathbb{F} -adapted by the same kind of reasoning as in section a.. That, $Y_t \in L^1(\Omega, \mathcal{F}, P)$ follows from the fact that $|\cos(x)| \leq 1$, we have

$$\mathbb{E}[|Y_t|] = \mathbb{E}\left[\left|e^{t/2} \cos(W_t)\right|\right] = e^{t/2} \mathbb{E}[|\cos(W_t)|] \leq e^{t/2} < \infty.$$

To check the martingale property we will use Itô's formula. Note that $Y_t = f(t, W_t)$ where $f(t, x) = e^{t/2} \cos(x) \in C^{1,2}([0, T] \times \mathbb{R})$ and $\partial_t f = \frac{1}{2}f$, $\partial_x f(t, x) = -e^{t/2} \sin(x)$ and $\partial_{xx} f = -f$. Hence,

$$\begin{aligned} Y_t &= f(t, W_t) = 1 + \int_0^t \left\{ \partial_t f(s, W_s) + \frac{1}{2} \partial_{xx} f(s, W_s) \right\} ds + \int_0^t \partial_x f(s, W_s) dW_s \\ &= 1 - \int_0^t e^{s/2} \sin(W_s) dW_s. \end{aligned}$$

As $e^{s/2} \sin(W_s)$ is measurable and adapted and

$$\mathbb{E} \left[\int_0^T \left| e^{t/2} \sin(W_t) \right|^2 dt \right] \leq \mathbb{E} \left[\int_0^T e^t dt \right] \leq e^T T < \infty,$$

we have that $e^{t/2} \sin(W_t) \in L_{a,T}^2$ and the Itô integral is a martingale.

- (c) $Z_t = W_t^2 - t$, $t \in [0, T]$: Z is \mathbb{F} -adapted by the same kind of reasoning as in section *a.* Z is integrable because

$$\mathbb{E}[|Z_t|] \leq \mathbb{E}[W_t^2] + t = 2t < \infty.$$

To check the martingale property we could use Itô's formula or the property that a Brownian motion has independent increments.

$$\begin{aligned} \mathbb{E}[Z_t | \mathcal{F}_s] &= \mathbb{E}[W_t^2 - t | \mathcal{F}_s] = \mathbb{E}[(W_t - W_s + W_s)^2 | \mathcal{F}_s] - t \\ &= \mathbb{E}[(W_t - W_s)^2 | \mathcal{F}_s] - \mathbb{E}[2(W_t - W_s)W_s | \mathcal{F}_s] + \mathbb{E}[W_s^2 | \mathcal{F}_s] - t \\ &= \mathbb{E}[(W_t - W_s)^2] - 2W_s \mathbb{E}[(W_t - W_s) | \mathcal{F}_s] + W_s^2 - t \\ &= t - s - 2W_s \mathbb{E}[(W_t - W_s)] + W_s^2 - t = W_s^2 - s = Z_s, \end{aligned}$$

where we have used that $W_t - W_s$ is independent of \mathcal{F}_s , that if V is independent of \mathcal{G} one has that $\mathbb{E}[V | \mathcal{G}] = \mathbb{E}[V]$, that W_s is \mathcal{F}_s -measurable and that W is a centered process.

- (d) $G_t = e^{W_t} - 1 - \frac{1}{2} \int_0^t e^{W_s} ds$, $t \in [0, T]$: G is \mathbb{F} -adapted because e^{W_t} is $\sigma(W_t)$ -measurable and $\sigma(W_t) \subset \mathcal{F}_t$. Moreover, $\int_0^t e^{W_s} ds$ is \mathcal{F}_t measurable because (using the definition of Riemann integrable function) is a P -a.s. limit of \mathcal{F}_t -measurable random variables. In other words, G_t only depends on the values of W up to time t . G is integrable because W_t (and W_s) has moments exponential moments of all orders. The martingale property follows by applying Itô's formula to $g(W_t)$ with the function $g(x) = e^x$. Note, $\partial_t g = 0$, $\partial_x g = \partial_{xx} g = g$. Hence,

$$g(W_t) = e^{W_t} = 1 + \int_0^t e^{W_s} dW_s + \frac{1}{2} \int_0^t e^{W_s} ds,$$

which yields that $G_t = \int_0^t e^{W_s} dW_s$. As e^{W_t} is measurable, adapted and

$$\mathbb{E} \left[\int_0^T |e^{W_t}|^2 dt \right] = \int_0^T \mathbb{E} [e^{2W_t}] dt = \int_0^T e^{\frac{4t}{2}} dt \leq e^{2T} T < \infty.$$

Hence, $e^{W_t} \in L_{a,T}^2$ and G_t is a martingale (because the Itô integral of a process in $L_{a,T}^2$ is a martingale).

- (e) $H_t = \exp \left(\int_0^t f_s dW_s - \frac{1}{2} \int_0^t f_s^2 ds \right)$, $t \in [0, T]$, $f \in L^2([0, T])$ deterministic: H is \mathbb{F} -adapted because $\exp(\int_0^t f_s dW_s)$ is \mathcal{F}_t -measurable as the Itô integrals is an \mathbb{F} -adapted process. By exercise 3., the law of $\int_0^t f_s dW_s$ is $\mathcal{N} \left(0, \int_0^t f_s^2 ds \right)$ because f is deterministic and square integrable. This yields that H is integrable. To check the martingale property we can repeat the same arguments as in section *a.* or use Itô's formula to $h(x) = \exp(x)$ applied to the Itô process $\int_0^t f_s dW_s - \frac{1}{2} \int_0^t f_s^2 ds$.

5. The square integrability of M ensure that the conditional expectation exists. The result follows using the basic properties of the conditional expectation and expanding $(M_t - M_s)^2$. We have that

$$\begin{aligned}\mathbb{E}[(M_t - M_s)^2 | \mathcal{F}_s] &= \mathbb{E}[M_t^2 - 2M_s M_t + M_s^2 | \mathcal{F}_s] \\ &= \mathbb{E}[M_t^2 | \mathcal{F}_s] - 2M_s \mathbb{E}[M_t | \mathcal{F}_s] + M_s^2 \\ &= \mathbb{E}[M_t^2 | \mathcal{F}_s] - 2M_s^2 + M_s^2 \\ &= \mathbb{E}[M_t^2 - M_s^2 | \mathcal{F}_s],\end{aligned}$$

where we have used that M_s and M_s^2 are \mathcal{F}_s -measurable and $\mathbb{E}[M_t | \mathcal{F}_s] = M_s$, the martingale property of M .

6. $Y_t = \varphi(M_t)$ where φ is a convex function and M is an \mathbb{F} -martingale. Y is integrable by assumption. Note that as φ is convex it is continuous and, hence, Borel measurable. Therefore, Y_t is $\sigma(M_t)$ -measurable and, as M is \mathbb{F} -adapted, we have that Y_t is \mathcal{F}_t -measurable, which yields that Y is \mathbb{F} -adapted. Finally the submartingale property follows from the conditional Jensen's inequality and the fact that M is a martingale, i.e., if $h(V) \in L^1(\Omega, \mathcal{F}, P)$ and \mathcal{G} is a sub- σ -algebra of \mathcal{F} we have that $\mathbb{E}[h(V) | \mathcal{G}] \geq h(\mathbb{E}[V | \mathcal{G}])$. Let's write it:

$$\mathbb{E}[Y_t | \mathcal{F}_s] = \mathbb{E}[\varphi(M_t) | \mathcal{F}_s] \geq \varphi(\mathbb{E}[M_t | \mathcal{F}_s]) = \varphi(M_s) = Y_s.$$

7. Let $\mathbb{F}^X = \{\mathcal{F}_t^X = \sigma(X_s : 0 \leq s \leq t)\}_{t \in \mathbb{R}_+}$ and $\mathbb{G}^X = \{\mathcal{F}_t^X = \sigma(X_v - X_u : 0 \leq u \leq v \leq t)\}_{t \in \mathbb{R}_+}$ the natural filtrations generated by the process X and by the increments of the process X . These filtrations are actually the same because for any $0 \leq t_1 \leq t_2 \leq \dots \leq t_n \in \mathbb{R}_+, n \in \mathbb{N}$, we have that $\sigma(X_{t_1}, X_{t_2}, \dots, X_{t_n}) = \sigma(X_{t_1}, X_{t_2} - X_{t_1}, \dots, X_{t_n} - X_{t_{n-1}})$ (note that there is a bijection between these two vectors). The hypothesis in this problem is that the process X has constant mean ($\mathbb{E}[X_t] = m, t \in \mathbb{R}_+$) and independent increments. The independent increments property can be written as follows: for all $s \leq t$ the random variable $X_t - X_s$ is independent of all random variables $X_v - X_u$ with $0 \leq u \leq v \leq s$. Therefore, we have that $X_t - X_s$ is independent of \mathcal{G}_s^X . Hence,

$$\mathbb{E}[X_t - X_s | \mathcal{F}_s^X] = \mathbb{E}[X_t - X_s | \mathcal{G}_s^X] = \mathbb{E}[X_t - X_s] = \mathbb{E}[X_t] - \mathbb{E}[X_s] = 0,$$

and we can conclude that X is a martingale (with respect to its natural filtration \mathcal{F}_t^X).

8. Let $X \in L^p(\Omega, \mathcal{F}, P)$ for some $p \geq 1$ and \mathbb{F} be a filtration in the probability space (Ω, \mathcal{F}, P) . Then $M_t = \mathbb{E}[X | \mathcal{F}_t]$ is a \mathbb{F} -martingale. M is \mathbb{F} -adapted by construction. We prove the p -th integrability of M (which implies the integrability of M). It follows by the conditional Jensen's inequality applied to the convex function $\varphi(x) = |x|^p$, the conservation of expectation property of the conditional expectation and the hypothesis $X \in L^p(\Omega, \mathcal{F}, P)$,

$$\mathbb{E}[|M_t|^p] = \mathbb{E}[|\mathbb{E}[X | \mathcal{F}_t]|^p] \leq \mathbb{E}[\mathbb{E}[|X|^p | \mathcal{F}_t]] = \mathbb{E}[|X|^p] < \infty.$$

The martingale property of M follows from the tower property of the conditional expectation

$$\mathbb{E}[M_t | \mathcal{F}_s] = \mathbb{E}[\mathbb{E}[X | \mathcal{F}_t] | \mathcal{F}_s] = \mathbb{E}[X | \mathcal{F}_s] = M_s.$$

9. For this exercise I only give the solution. $W = (W_t^1, W_t^2, W_t^3)_{t \in \mathbb{R}_+}$ is a 3-dimensional Brownian motion.

- (a) $u_1(t, W_t) = 5 + 4t + \exp(3W_t^1)$ has the following Itô differential

$$\begin{aligned}du_1(t, W_t) &= 3 \exp(3W_t^1) dW_t^1 + \left\{ 4 + \frac{9}{2} \exp(3W_t^1) \right\} dt, \\ u_1(0, 0) &= 5.\end{aligned}$$

- (b) $u_2(t, W_t) = (W_t^2)^2 + (W_t^3)^2$ has the following Itô differential

$$\begin{aligned}du_2(t, W_t) &= 2W_t^2 dW_t^2 + 2W_t^3 dW_t^3 + 2dt, \\ u_2(0, 0) &= 0.\end{aligned}$$

(c) $u_3(t, W_t) = \log(u_1(t, W_t)u_2(t, W_t))$ has the following Itô differential

$$\begin{aligned} du_3(t, W_t) &= \frac{3 \exp(3W_t^1)}{5 + 4t + \exp(3W_t^1)} dW_t^1 + \frac{2W_t^2}{(W_t^2)^2 + (W_t^3)^2} dW_t^2 \\ &+ \frac{2W_t^3}{(W_t^2)^2 + (W_t^3)^2} dW_t^3 + \left\{ \frac{4 + \frac{9}{2} \exp(3W_t^1)}{5 + 4t + \exp(3W_t^1)} \right. \\ &+ \frac{2}{(W_t^2)^2 + (W_t^3)^2} - \frac{9}{2} \frac{\exp(6W_t^1)}{(5 + 4t + \exp(3W_t^1))^2} \\ &\left. - \frac{2(W_t^2)^2 + 2(W_t^3)^2}{((W_t^2)^2 + (W_t^3)^2)^2} \right\} dt \end{aligned}$$

10. Recall that a discrete time, integrable and $\{\mathcal{H}_n\}_{n \geq 0}$ -adapted process $\{Z_n\}_{n \geq 0}$ is a $\{\mathcal{H}_n\}$ -martingale if $\mathbb{E}[Z_n | \mathcal{H}_{n-1}] = Z_{n-1}$ for all $n \geq 1$. G_n is $\{\mathcal{F}_n\}$ -adapted because $H_i(M_i - M_{i-1})$ is \mathcal{F}_i -measurable for $0 \leq i \leq n$ and, hence, \mathcal{F}_n -measurable. Next step is to check that $\mathbb{E}[|G_n|] < \infty$ for all $n \geq 1$. We have, using the triangular inequality and the fact that M is integrable because it is a martingale, that

$$\begin{aligned} \mathbb{E}[|G_n|] &= \mathbb{E} \left[\left| \sum_{i=1}^n H_i(M_i - M_{i-1}) \right| \right] \leq \sum_{i=1}^n \mathbb{E}[|H_i(M_i - M_{i-1})|] \\ &\leq \sum_{i=1}^n C_i \mathbb{E}[|(M_i - M_{i-1})|] \leq \sum_{i=1}^n C_i \{ \mathbb{E}[|M_i|] + \mathbb{E}[|M_{i-1}|] \} \\ &\leq 2 \sup_{0 \leq i \leq n} \mathbb{E}[|M_i|] \sum_{i=1}^n C_i < \infty, \end{aligned}$$

To check the martingale property we can write

$$\begin{aligned} \mathbb{E}[G_n | \mathcal{F}_{n-1}] &= \mathbb{E} \left[\sum_{i=1}^n H_i(M_i - M_{i-1}) | \mathcal{F}_{n-1} \right] \\ &= \mathbb{E}[G_{n-1} + H_n(M_n - M_{n-1}) | \mathcal{F}_{n-1}] \\ &= G_{n-1} + H_n \mathbb{E}[M_n - M_{n-1} | \mathcal{F}_{n-1}] \\ &= G_{n-1} + \mathbb{E}[M_n | \mathcal{F}_{n-1}] - M_{n-1} \\ &= G_{n-1} + M_{n-1} - M_{n-1} = G_{n-1}, \end{aligned}$$

where we have used that G_{n-1}, H_n and M_{n-1} are \mathcal{F}_{n-1} -measurable and M is a martingale.

11. In this exercise we have to find the Itô representation of some square integrable random variables, that is, if $F \in L^2(\Omega, \mathcal{F}_T, P)$ there exists a process $f \in L^2_{a,T}$ such that $F = \mathbb{E}[F] + \int_0^T f_s dW_s$.

(a) $F_1 = W_T$. We can write

$$W_T = \int_0^T dW_t = 0 + \int_0^T dW_t = \mathbb{E}[W_T] + \int_0^T 1 dW_t.$$

(b) $F_2 = W_T^2$. We can use Itô's formula to get that

$$\begin{aligned} W_T^2 &= W_0 + \int_0^T \frac{2}{2} dt + \int_0^T 2W_t dW_t \\ &= 0 + T + \int_0^T 2W_t dW_t = \mathbb{E}[W_T^2] + \int_0^T 2W_t dW_t. \end{aligned}$$

(c) $F_3 = e^{W_T}$. Here, the idea is to use that we know that $f(t, W_t) = \exp(W_t - \frac{t}{2})$ is a martingale so we can write it as an stochastic integral of some process in $L^2_{a,T}$. To find

such a process we use Itô's formula. We have that $\partial_t f(t, x) = -\frac{1}{2}f(t, x)$ and $\partial_x f(t, x) = \partial_{xx} f(t, x) = f(t, x)$. Therefore,

$$\exp(W_T - T/2) = 1 + \int_0^T \exp(W_t - t/2) dW_t,$$

which yields that

$$\begin{aligned} \exp(W_T) &= e^{T/2} + e^{T/2} \int_0^T \exp(W_t - t/2) dW_t \\ &= \mathbb{E}[\exp(W_T)] + \int_0^T \exp(W_t + (T-t)/2) dW_t. \end{aligned}$$

Note that $e^{T/2}$ can go inside the stochastic integral because is deterministic.

(d) $F_4 = \int_0^T W_t dt$. By the integration by parts formula one can write

$$TW_T = \int_0^T W_t dt + \int_0^T t dW_t,$$

which yields

$$\begin{aligned} \int_0^T W_t dt &= TW_T - \int_0^T t dW_t = T \int_0^T dW_t - \int_0^T t dW_t \\ &= \int_0^T (T-t) dW_t = \mathbb{E} \left[\int_0^T W_t dt \right] + \int_0^T (T-t) dW_t. \end{aligned}$$

Note that $\mathbb{E} \left[\int_0^T W_t dt \right] = \int_0^T \mathbb{E}[W_t] dt = \int_0^T 0 dt = 0$.

(e) $F_6 = \int_0^T t^2 W_t^2 dt$. The idea is to consider the process $Y_t = W_t^2 - t$ that we know it is a martingale. By Itô's formula we have that $dY_t = 2W_t dW_t$. On the other hand consider the process given by $dX_t = t^2 dt$ which is equal to $X_t = \frac{t^3}{3}$. Now, we can apply integration by parts formula to the process $X_t Y_t$, taking into account that $d(X_t)d(Y_t) = 0$, to get

$$\begin{aligned} \frac{T^3}{3}(W_T^2 - T) &= X_T Y_T = X_0 Y_0 + \int_0^T X_t dY_t + \int_0^T Y_t dX_t \\ &= 0 + \int_0^T \frac{2}{3} t^3 W_t dW_t + \int_0^T t^2 (W_t^2 - t) dt \\ &= \int_0^T \frac{2}{3} t^3 W_t dW_t + \int_0^T t^2 W_t^2 dt - \frac{T^4}{4}, \end{aligned}$$

but note that

$$\frac{T^3}{3}(W_T^2 - T) = \frac{T^3}{3} \int_0^T 2W_t dW_t = \int_0^T \frac{2}{3} T^3 W_t dW_t.$$

Hence, we get that

$$\begin{aligned} \int_0^T t^2 W_t^2 dt &= \frac{T^4}{4} + \int_0^T \frac{2}{3} T^3 W_t dW_t - \int_0^T \frac{2}{3} t^3 W_t dW_t \\ &= \mathbb{E} \left[\int_0^T t^2 W_t^2 dt \right] + \int_0^T \frac{2}{3} (T^3 - t^3) W_t dW_t, \end{aligned}$$

because

$$\mathbb{E} \left[\int_0^T t^2 W_t^2 dt \right] = \int_0^T t^2 \mathbb{E}[W_t^2] dt = \int_0^T t^3 dt = \frac{T^4}{4}.$$

12. $P|_{\mathcal{F}_t}$ and $Q|_{\mathcal{F}_t}$ are probabilities on (Ω, \mathcal{F}_t) that are constructed by considering the restriction of P and Q , respectively, to \mathcal{F}_t , that is, $P|_{\mathcal{F}_t}(A) = P(A)$ and $Q|_{\mathcal{F}_t}(A) = Q(A)$, $A \in \mathcal{F}_t$. Hence,

$$A \in \mathcal{F}_t \text{ such that } 0 = P|_{\mathcal{F}_t}(A) = P(A) \xrightarrow{Q \ll P} 0 = Q(A) = Q|_{\mathcal{F}_t}(A),$$

and we get that $Q|_{\mathcal{F}_t} \ll P|_{\mathcal{F}_t}$. Define $Z_T = \frac{dQ}{dP}$ and $Z_t = \mathbb{E}_P[Z_T | \mathcal{F}_t]$. By exercise 8., we know that Z is a \mathbb{F} -martingale. Moreover, for all $A \in \mathcal{F}_t$ we have that

$$\begin{aligned} Q|_{\mathcal{F}_t}(A) &= Q(A) = \mathbb{E}_Q[\mathbf{1}_A] = \mathbb{E}_P[Z_T \mathbf{1}_A] = \mathbb{E}_P[E[Z_T \mathbf{1}_A | \mathcal{F}_t]] \\ &= \mathbb{E}_P[E[Z_T | \mathcal{F}_t] \mathbf{1}_A] = \mathbb{E}_P[Z_t \mathbf{1}_A] = \mathbb{E}_{P|_{\mathcal{F}_t}}[Z_t \mathbf{1}_A], \end{aligned}$$

which yields that $Z_t = \frac{dQ|_{\mathcal{F}_t}}{dP|_{\mathcal{F}_t}}$, $P|_{\mathcal{F}_t}$ -a.s. Note that we have used that $\mathbb{E}_P[X] = \mathbb{E}_{P|_{\mathcal{F}_t}}[X]$ for any X that is \mathcal{F}_t -measurable. One can check this property by using the definitions of Lebesgue integral and the fact that $P|_{\mathcal{F}_t}$ coincides with P on any \mathcal{F}_t -measurable set. Finally, we have to prove that Y is a martingale under $Q \iff ZY$ is a martingale under P .

\Rightarrow) By exercise 32 in List 1 (see the solution of the optional exercise) We have that

$$\mathbb{E}_Q[Y_t | \mathcal{F}_s] \mathbb{E}_P[Z_t | \mathcal{F}_s] = \mathbb{E}_P[Z_t Y_t | \mathcal{F}_s], \quad s < t. \quad (1)$$

Note that, as Y is a martingale under Q we get $\mathbb{E}_Q[Y_t | \mathcal{F}_s] = Y_s$ and as Z is a martingale under P we get $\mathbb{E}_P[Z_t | \mathcal{F}_s] = Z_s$. Hence, the left hand side of equation (1) is equal to $Z_s Y_s$ and we can conclude that ZY is a martingale under P .

\Leftarrow) As ZY and Z are martingales under P , we get that $\mathbb{E}_P[Z_t Y_t | \mathcal{F}_s] = Z_s Y_s$ and $\mathbb{E}_P[Z_t | \mathcal{F}_s] = Z_s$ and equation (1) is equal to

$$\mathbb{E}_Q[Y_t | \mathcal{F}_s] Z_s = Z_s Y_s \iff \mathbb{E}_Q[Y_t | \mathcal{F}_s] = Y_s.$$

Therefore, we can conclude that Y is a martingale under Q .