Answers to the examination problems in ECON 3120/4120, 6 June 2006

Problem 1

The first and second order derivatives of f are

$$f_1'(x,y) = (2x - ay)e^y,$$

$$f_2'(x,y) = (x^2 - axy - ax)e^y = x(x - ay - a)e^y,$$

$$f_{11}''(x,y) = 2e^y,$$

$$f_{12}''(x,y) = (2x - ay - a)e^y,$$

$$f_{22}''(x,y) = (x^2 - axy - 2ax)e^y = x(x - ay - 2a)e^y.$$

The stationary points are the solutions of the following system:

$$(1) 2x - ay = 0$$

$$(2) x(x-ay-a) = 0$$

If x = 0, then (1) gives y = 0 (because $a \neq 0$). If $x \neq 0$, then (2) gives x = ay + a, and then (1) gives ay + 2a = 0, i.e. y = -2, and so x = ay + a = -a.

Conclusion: There are two stationary points, (0, 0) and (-a, -2).

(a) To determine the nature of a stationary point (x_0, y_0) we use the secondderivative test, with $A = f_{11}''(x_0, y_0)$, $B = f_{12}''(x_0, y_0)$, and $C = f_{22}''(x_0, y_0)$. The test gives

Point	A	В	C	$AC - B^2$	Result
(0, 0)	2	-a	0	$-a^2$	Saddle point
(-a, -2)	$2e^{-2}$	$-ae^{-2}$	$a^2 e^{-2}$	$a^2 e^{-4}$	Local min. pt.

(b) $(x^*, y^*) = (-a, -2)$, and therefore

$$f^*(a) = f(-a, -2) = -a^2 e^{-2}$$
 and $df^*(a)/da = -2ae^{-2}$.

On the other hand, $\hat{f}(x, y, a) = (x^2 - axy)e^y$, and

$$\hat{f}'_3(x,y,a) = -xye^y$$
 and $\hat{f}'_3(x^*,y^*,a) = -x^*y^*e^{y^*} = -2ae^{-2}.$

Thus the equation $\hat{f}'_3(x, y, a) = df^*(a)/da$ is true (as the envelope theorem also tells us).

Problem 2

(a)

Gaussian elimination:

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 1 & 3 & 2 \\ 1 & t & -1 & 4 \end{pmatrix} \xleftarrow{-2 & -1} \sim \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & -3 & -3 & -6 \\ 0 & t - 2 & -4 & 0 \end{pmatrix} \times (-\frac{1}{3})$$
$$\sim \begin{pmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 1 & 2 \\ 0 & t - 2 & -4 & 0 \end{pmatrix} \xleftarrow{-2} 2 - t \sim \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 2 \\ 0 & 0 & -t - 2 & 4 - 2t \end{pmatrix}$$

The final matrix corresponds to the equation system

$$x + z = 0$$

$$y + z = 2$$

$$(-t - 2)z = 4 - 2t$$

With t = -2, the last equation becomes 0 = 8, which is impossible. Thus, there is no solution if t = -2.

If $t \neq -2$, then the system has a unique solution: The last equation gives

$$z = \frac{4-2t}{-t-2} = \frac{2t-4}{t+2},$$

and then

$$y = 2 - z = \frac{2(t+2) - (2t-4)}{t+2} = \frac{8}{t+2}$$
 and $x = -z = \frac{4-2t}{t+2}$.

(b)
$$2x_t \ge y_t \iff 2x_t - y_t \ge 0 \iff \frac{2(4-2t)-8}{t+2} \ge 0 \iff \frac{4t}{t+2} \le 0.$$

A simple argument with a sign diagram shows that this inequality holds if and only if $-2 < t \leq 0$. (t = -2 is excluded because the fractions are not defined there.)

Problem 3

(a) The equation is a linear first-order equation which can be written in standard form as $\dot{x} + a(t)x = b(t)$ with

$$a(t) = \frac{1}{t(t-1)} = \frac{1}{t-1} - \frac{1}{t}$$
 and $b(t) = \frac{te^t}{t-1}$.

The general solution can be found by means of formula (5.4.6) in FMEA or (1.4.6) in MA II. We shall need one indefinite integral of a(t) (no arbitrary constant necessary):

$$A(t) = \int a(t) dt = \int \left(\frac{1}{t-1} - \frac{1}{t}\right) dt$$

= $\ln|t-1| - \ln|t| = \ln(1-t) - \ln t = \ln\frac{1-t}{t}$.

(Remember that t lies between 0 and 1.) Then

$$e^{\int a(t) dt} = e^{A(t)} = \frac{1-t}{t}$$
 and $e^{-\int a(t) dt} = \frac{t}{1-t}$

The solution formula in the book now yields the general solution:

$$\underline{\underline{x(t)}} = \frac{t}{1-t} \left(C + \int \frac{1-t}{t} \frac{te^t}{t-1} dt \right) = \frac{t}{1-t} \left(C - \int e^t dt \right) = \frac{t(C-e^t)}{\underbrace{1-t}}.$$

(b) It is clear that $\lim_{t\to 0^+} x(t) = 0$ for all values of C. But what about $\lim_{t\to 1^-} x(t)$? The expression for x(t) is a fraction whose denominator, 1-t, tends to 0 as a limit as $t\to 1^-$. Thus for x(t) to tend to a limit, the numerator, $t(C-e^t)$, must also tend to 0. That is, we must have C = e. With this value of C, we get

$$x(t) = t \frac{e - e^t}{1 - t},$$

and by l'Hôpital's rule,

$$\lim_{t \to 1^{-}} x(t) = 1 \cdot \lim_{t \to 1^{-}} \frac{e - e^{t}}{1 - t} = \frac{0}{0} = \lim_{t \to 1^{-}} \frac{-e^{t}}{-1} = e.$$

Problem 4

(a) Integration gives

$$S = \int_0^T e^{-rx} (e^{gT - gx} - 1) \, dx = \int_0^T e^{gT - (r+g)x} \, dx - \int_0^T e^{-rx} \, dx$$
$$= - \Big|_0^T \frac{e^{gT - (r+g)x}}{r+g} + \Big|_0^T \frac{e^{-rx}}{r} = \frac{e^{gT} - e^{-rT}}{r+g} + \frac{e^{-rT} - 1}{r}$$

and therefore

$$r(r+g)S = r(e^{gT} - e^{-rT}) + (r+g)(e^{-rT} - 1)$$

= $r(e^{gT} - e^{-rT}) - (r+g)(1 - e^{-rT})$

(b) The given equation can be written as F(r, g, S, T) = 0, where

$$F(r, g, S, T) = r(e^{gT} - e^{-rT}) - (r+g)(1 - e^{-rT}) - r(r+g)S$$
$$= re^{gT} - (r+g) + ge^{-rT} - r(r+g)S.$$

It follows that

$$\begin{split} \frac{\partial T}{\partial g} &= -\frac{\partial F/\partial g}{\partial F/\partial T} = -\frac{F_2'(r,g,S,T)}{F_4'(r,g,S,T)} = -\frac{rTe^{gT} - 1 + e^{-rT} - rS}{rge^{gT} - rge^{-rT}} \\ &= \frac{rS + 1 - rTe^{gT} - e^{-rT}}{rg(e^{gT} - e^{-rT})} \,. \end{split}$$