

# The Lucas-critique .

## Reference note to lecture 8 in ECON 5101/9101, Time Series Econometrics

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### 1 Introduction

Lucas (1976), together with Sims (1980), are two of the most influential and “formative” papers in the field of applied macroeconomics and econometrics. We referred to Sim’s paper in the VAR lecture. Lucas’ offering from 1976 contains what has become known as the *Lucas-critique*. This note contains a brief exposition, and notes the line back to Haavelmo (1944), and to the econometric concept of super exogeneity.

### 2 Invariance and the Lucas critique

The essence in the Lucas-critique can be shown by starting with the simple relationship

$$(2.1) \quad y_t = \beta_0 x_t + \eta_t,$$

which we assume is estimated by OLS.  $\eta_t$  denotes a disturbance whose properties depend on the data generating process, which is assumed to be given by

$$(2.2) \quad y_t = \beta_0^* E(x_t | \mathcal{I}_{t-1}) + \varepsilon_t$$

$$(2.3) \quad x_t = a_{22} x_{t-1} + \epsilon_{xt},$$

where  $-1 < a_{22} < 1$ .  $\varepsilon_t$  and  $\epsilon_{xt}$  have zero means and are uncorrelated.  $\mathcal{I}_{t-1}$  denotes the information set used to form rational expectations. In this simple case we can replace  $E(x_t | \mathcal{I}_{t-1})$  by the more practical notation  $E(x_t | x_{t-1})$ . By assumption we also have

$$E(\varepsilon_t | x_t) = 0.$$

Without loss of generality, assume that  $\varepsilon_t$  and  $\epsilon_{xt}$  are independent and normally distributed.  $y_t$  is then a normal variable with mean:

$$E(y_t | x_{t-1}) = \alpha_{22} \beta_0^* x_{t-1},$$

and  $x_t$  has also a normal distribution with mean

$$E(x_t | x_{t-1}) = a_{22} x_{t-1}.$$

The conditional mean of  $y_t$  given  $x_t$  becomes

$$(2.4) \quad E(y_t | x_t) \equiv \mu_{Y|X} = \beta_0^* x_t + E(\eta_t | x_t),$$

where  $E(\eta_t | x_t) \neq 0$ , since  $x_t$  must be correlated with  $\eta_t$  due to

$$\eta_t = \varepsilon_t - \beta_0^* \epsilon_{xt}$$

and the DGP (2.2) and (2.3). Specifically, we have

$$(2.5) \quad E(\eta_t | x_t) = -\beta_0^* E(\epsilon_{xt} | x_t)$$

since  $E(\varepsilon_t | x_t) = 0$  from the assumptions of the DGP-

With reference to the assumed normality we have the regression function:

$$E(\epsilon_{xt} | x_t) = \delta x_t$$

where

$$\delta = \frac{E(\epsilon_{xt} x_t)}{Var(x_t)} = \frac{\sigma_{\epsilon_{xt}}^2}{Var(x_t)}$$

and where  $\sigma_{\epsilon_{xt}}^2$  denotes the variance of  $\epsilon_{xt}$ . Subject to stationarity we have:

$$Var(x_t) = \frac{\sigma_{\epsilon_{xt}}^2}{1 - a_{22}^2}$$

The regression coefficient  $\delta$  is therefore

$$(2.6) \quad \delta = (1 - a_{22}^2).$$

Substitution into (2.4) of the expressions for  $E(\eta_t | X_t)$ , (2.5) and  $\delta$ , (2.6), give the conditional expectation for  $y_t$  when the DGP is characterized by rational expectations, (2.2) and (2.3):

$$(2.7) \quad \mu_{Y|X} = \beta_0^* x_t - \beta_0^* (1 - a_{22}^2) x_t = (\beta_0^* a_{22}^2) x_t.$$

The OLS estimator  $\hat{\beta}_0$  is as always consistent for the regression coefficient between  $y_t$  and  $x_t$ , but in this case that coefficient is not a single parameter but  $\beta_0^* a_{22}^2$ . Hence we get

$$(2.8) \quad \text{plim}(\hat{\beta}_0) = \beta_0^* a_{22}^2 < \beta_0^*, \text{ since } -1 < a_{22} < 1.$$

However, the real thrust of the Lucas-critique is that any change in the formation of expectations (changes in the  $a_{22}$  parameter) is predicted to lead to a change in  $\text{plim}(\hat{\beta}_0)$ . Since a main channel of policy (many would say the only) is the expectations channel, the estimator of  $\beta_0$  gives the wrong conclusions about how a policy change affects  $y_t$ .

The parameter  $\beta_0$  is not invariant to changes in expectations and so  $x_t$  in (2.1) is not super exogenous when the DGP is rational expectations driven as in (2.2) and (2.3).

In contrast to  $\beta_0$ , the parameter  $\beta_0^*$  is often called a ‘‘deep-structure parameter’’. It is invariant to interventions in the  $x_t$  process when the true DGP is (2.2) and (2.3).

### 3 The Lucas-critique as a possibility theorem—not a truism

The Lucas critique identifies one mechanism that can induce lack of invariance (and a low degree of autonomy) in the parameters of a conditional econometric model. In practice there are many others pitfalls as well. Omitted variables for example is a important (though mundane) cause of lack of invariance in econometric models, including those estimated by IV/GMM.

The exact set of assumptions is important when invariance. Assume for example that another theory is valid

$$y_t^p = \beta_0 x_t$$

where  $y_t^p$  is the agents' planned consumption, or price change. If  $y_t = y_t^p + \varepsilon_t$  and  $E(\varepsilon_t, x_t) = 0$ , then  $\text{plim}(\hat{\beta}_0) = \beta_0$  which is the relevant parameter for policy evaluation. Hence the force of the Lucas critique depends on the relevance of the underlying theory, which needs to be tested.

One approach to testing the force of the Lucas-critique is (simply) to check whether the predicted invariance occurs after a significant structural break in the marginal part of the model. We also refer to this as tests of invariance (and of super exogeneity).

### 4 The Lucas-critique and the Haavelmo-critique

Early in the history of econometrics Frisch and Haavelmo spent a lot of time conceptualizing terms like autonomy, confluence and invariance. The discussion in section 8 of Haavelmo (1944) an interesting read, in particular with the Lucas-critique in mind.

About the same time as Lucas' break-through, Leif Johansen also took on board the concept of (degree of) autonomy in his theory of economic planning, see Johansen (1977, Ch 4.6).

## References

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